

# Geometric Gaussian Processes

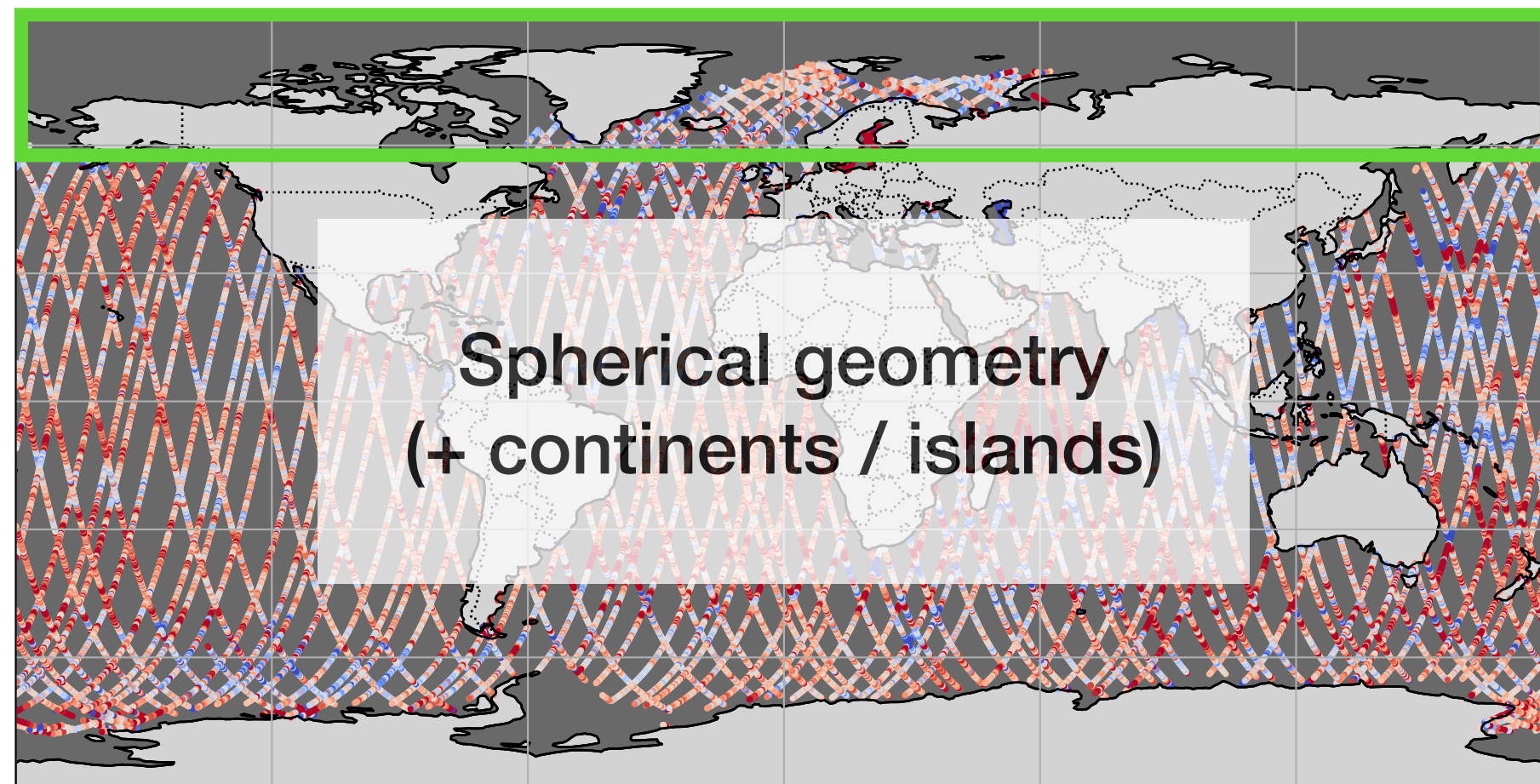
With applications to remote sensing observations

# New era for EO

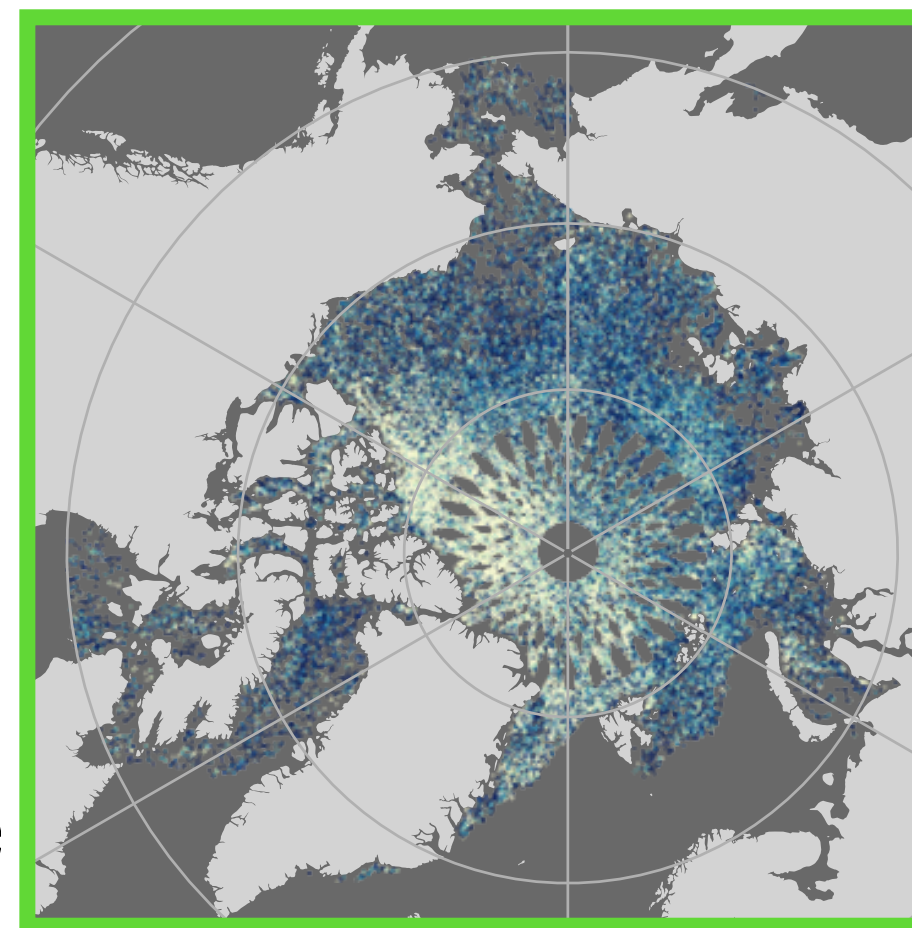
Innovation in satellite products calls for new approaches to extract information from them



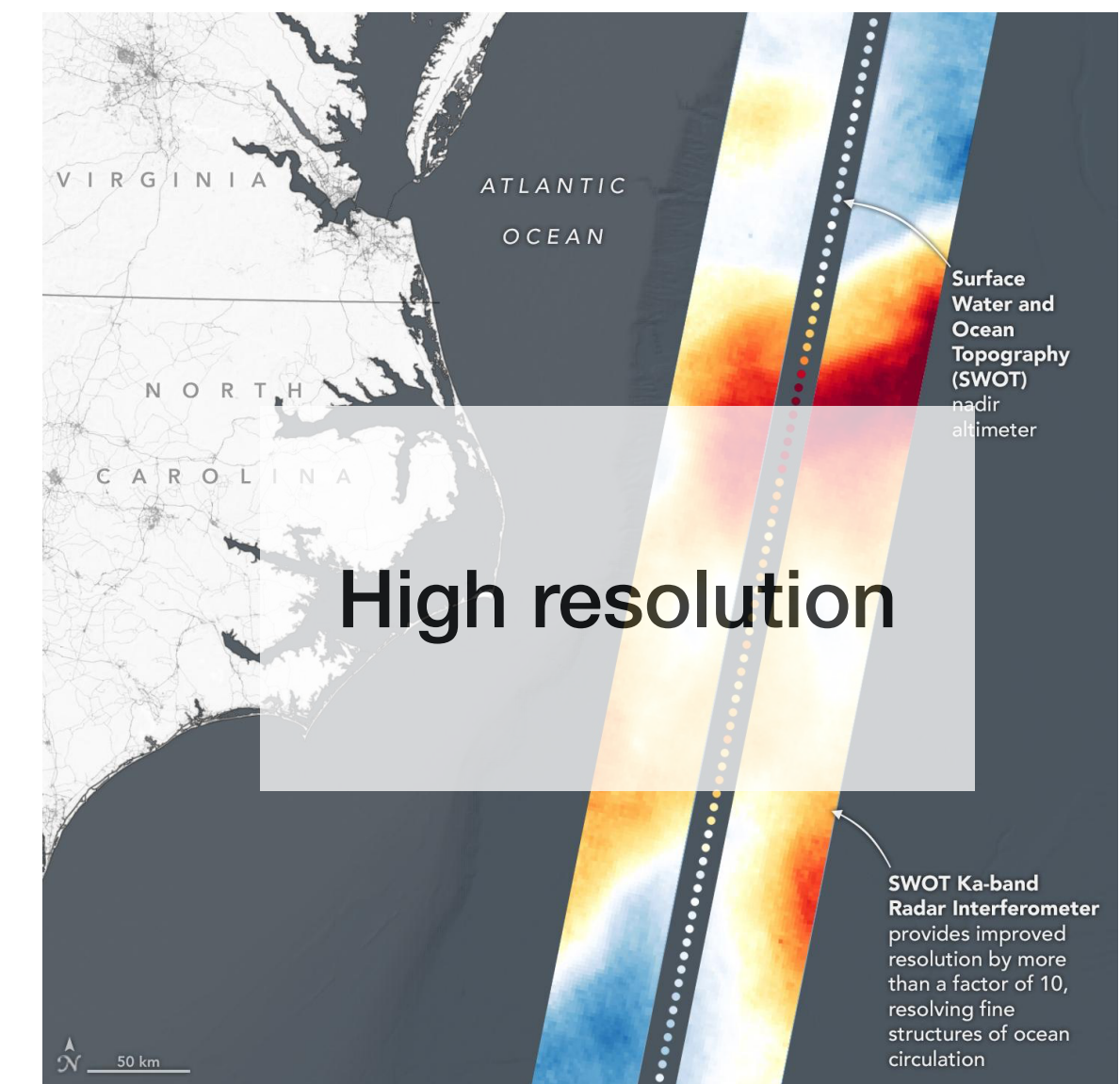
Aeolus project



Sentinel 3A and 3B



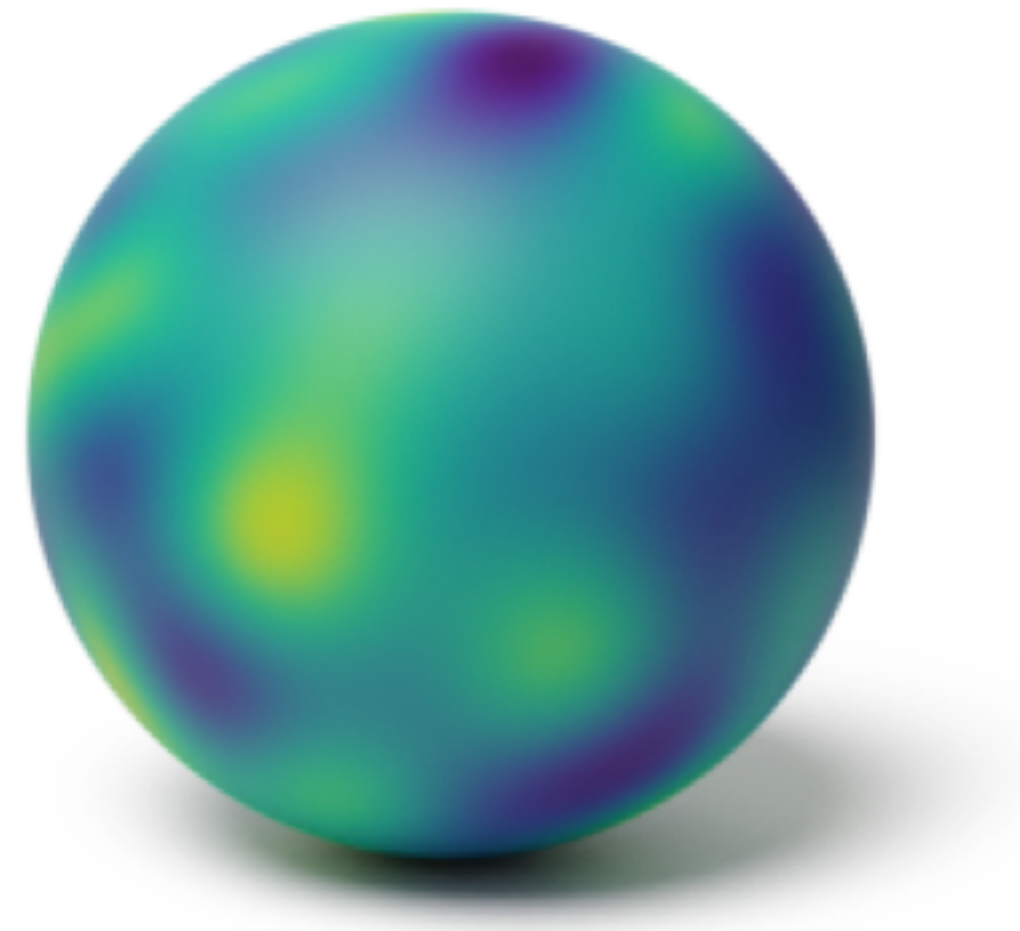
CryoSat 2



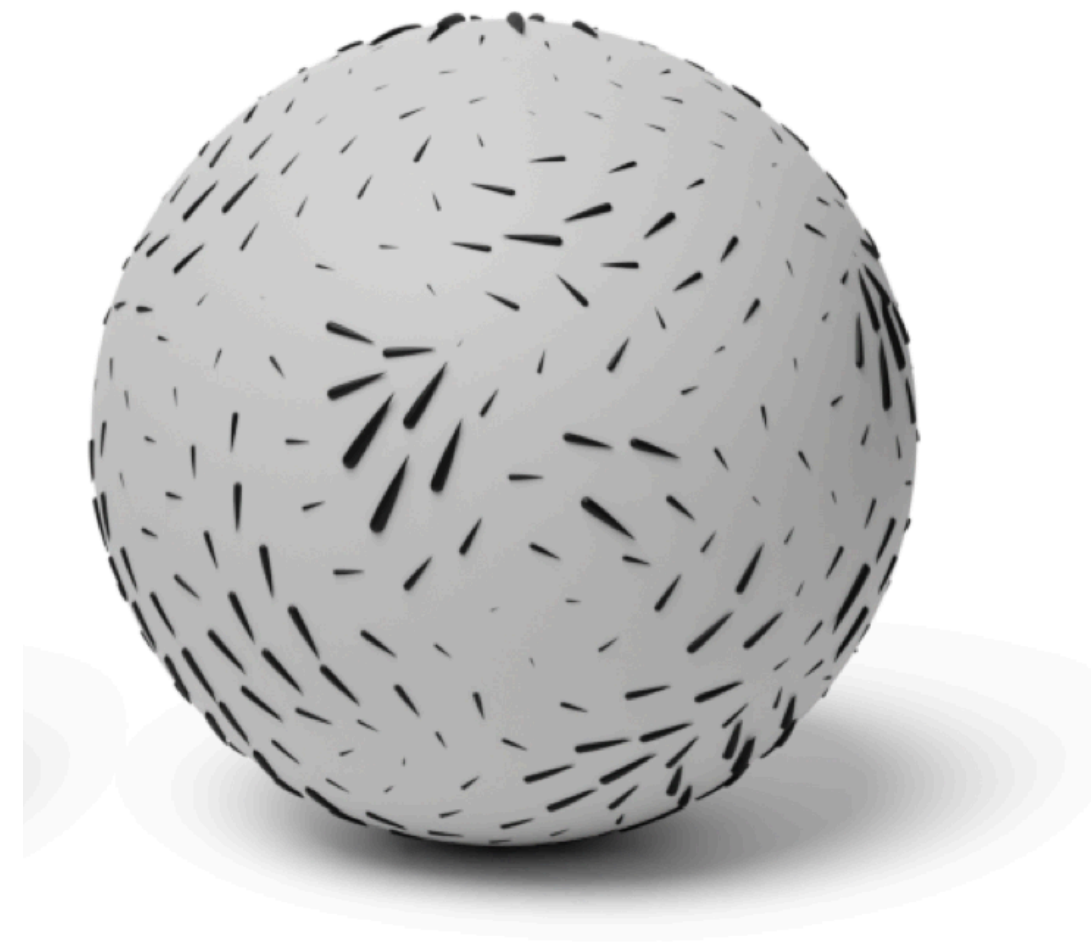
Sea Surface Height Anomaly (m)  
≤ -0.25    0    ≥ 0.25

SWOT mission

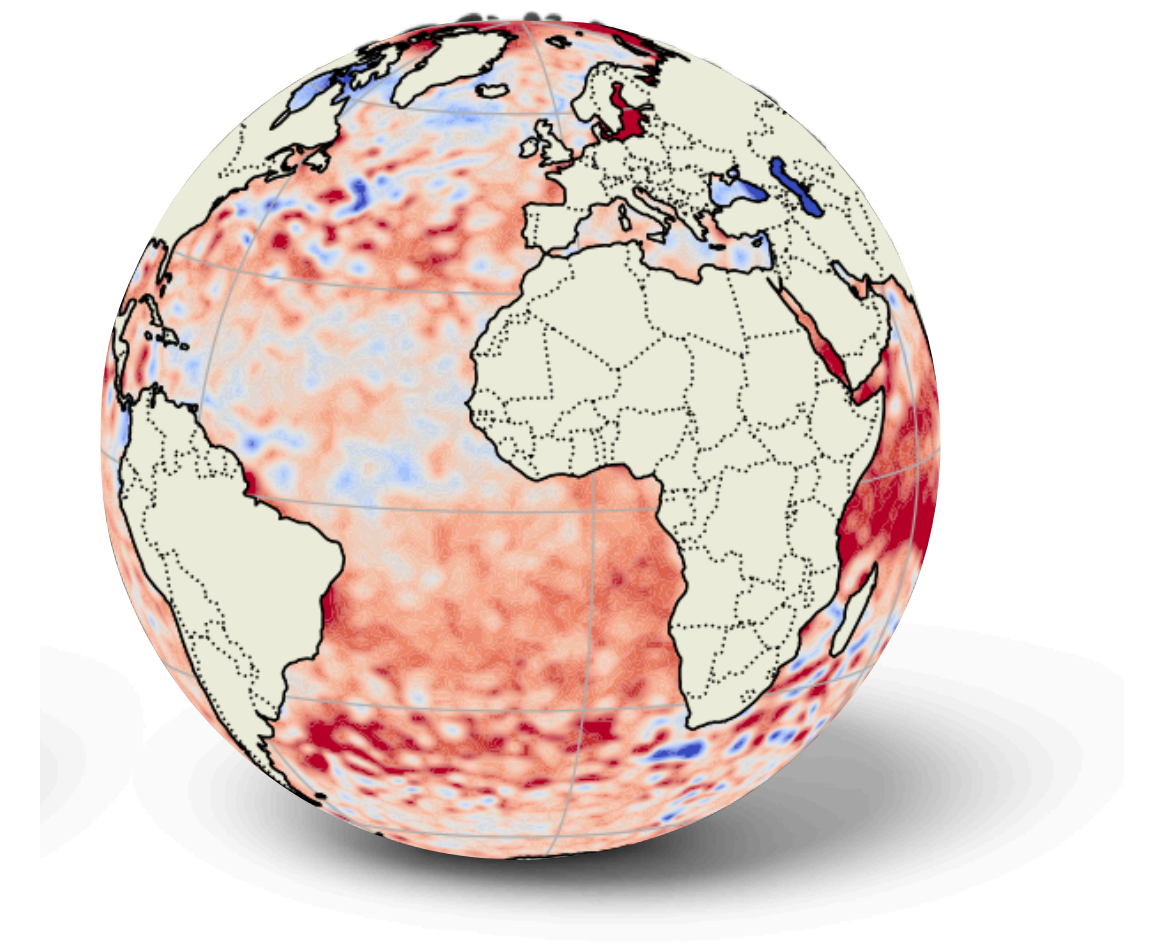
# Part 1



# Part 2



# Part 3



# 0.0. Gaussian processes

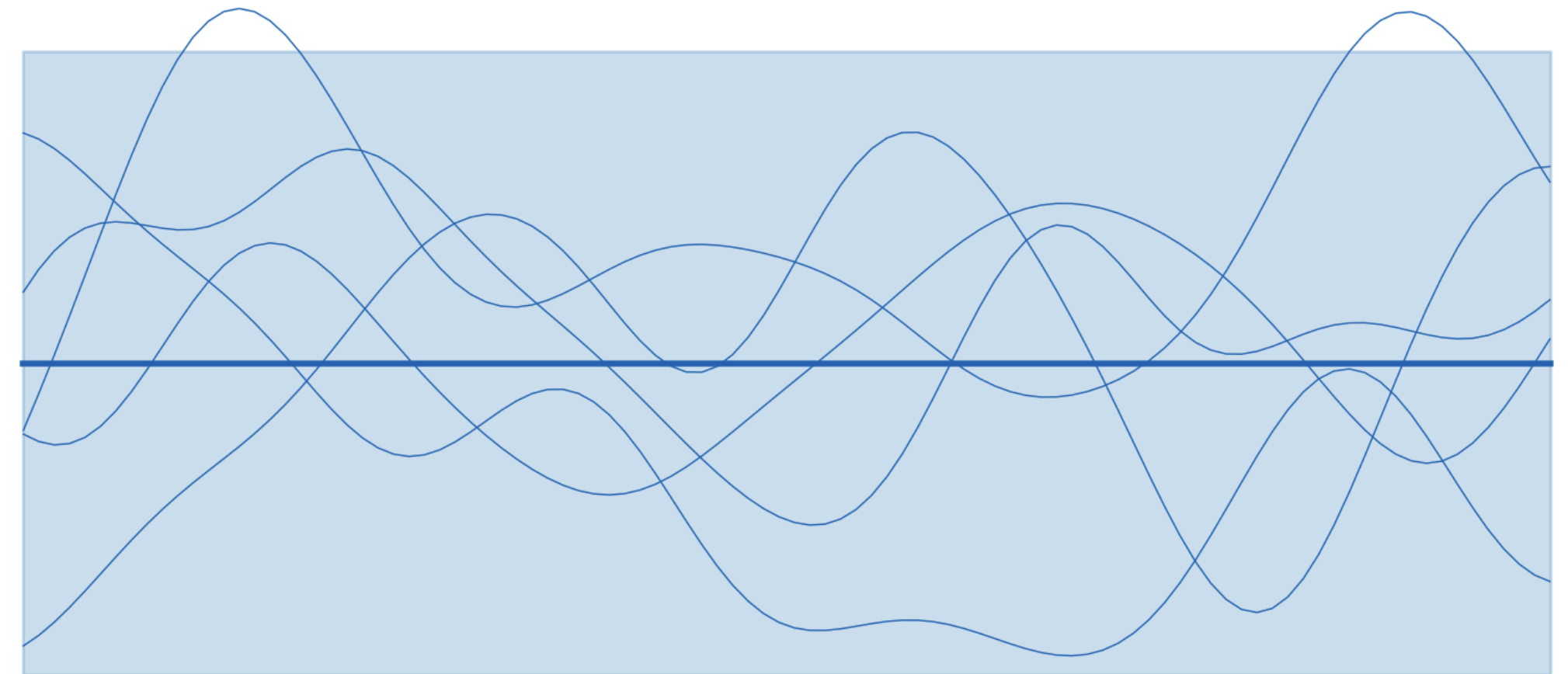
# Gaussian processes

Gaussian processes (GP) are random variables on the *space of functions*

A GP  $f : X \rightarrow \mathbb{R}$  is characterised by:

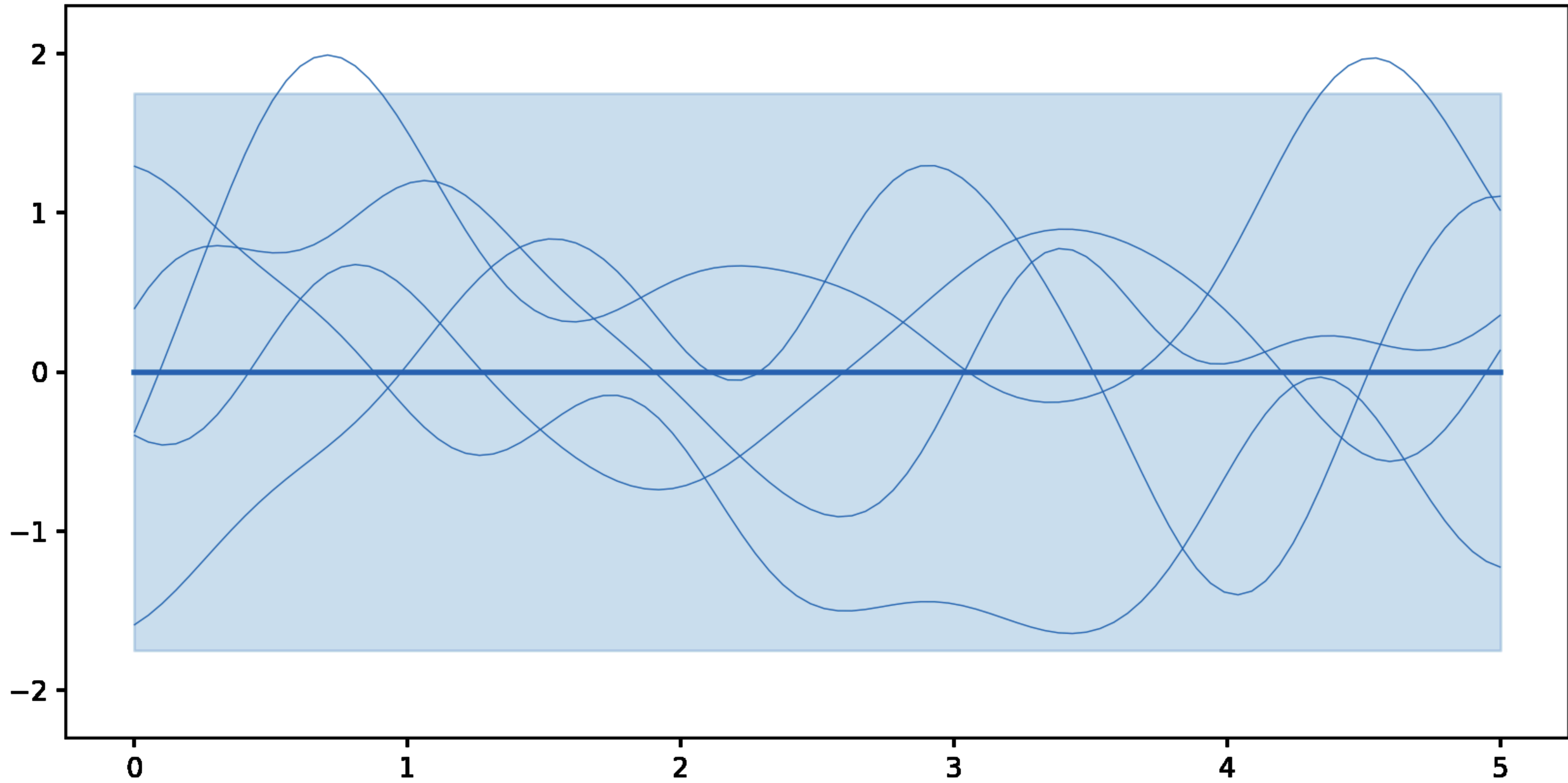
1. A mean function  $m(x) := \mathbb{E}[f(x)]$ , and
2. A kernel  $k(x, x') = \text{Cov}[f(x), f(x')]$ ,

which is *positive semidefinite*.



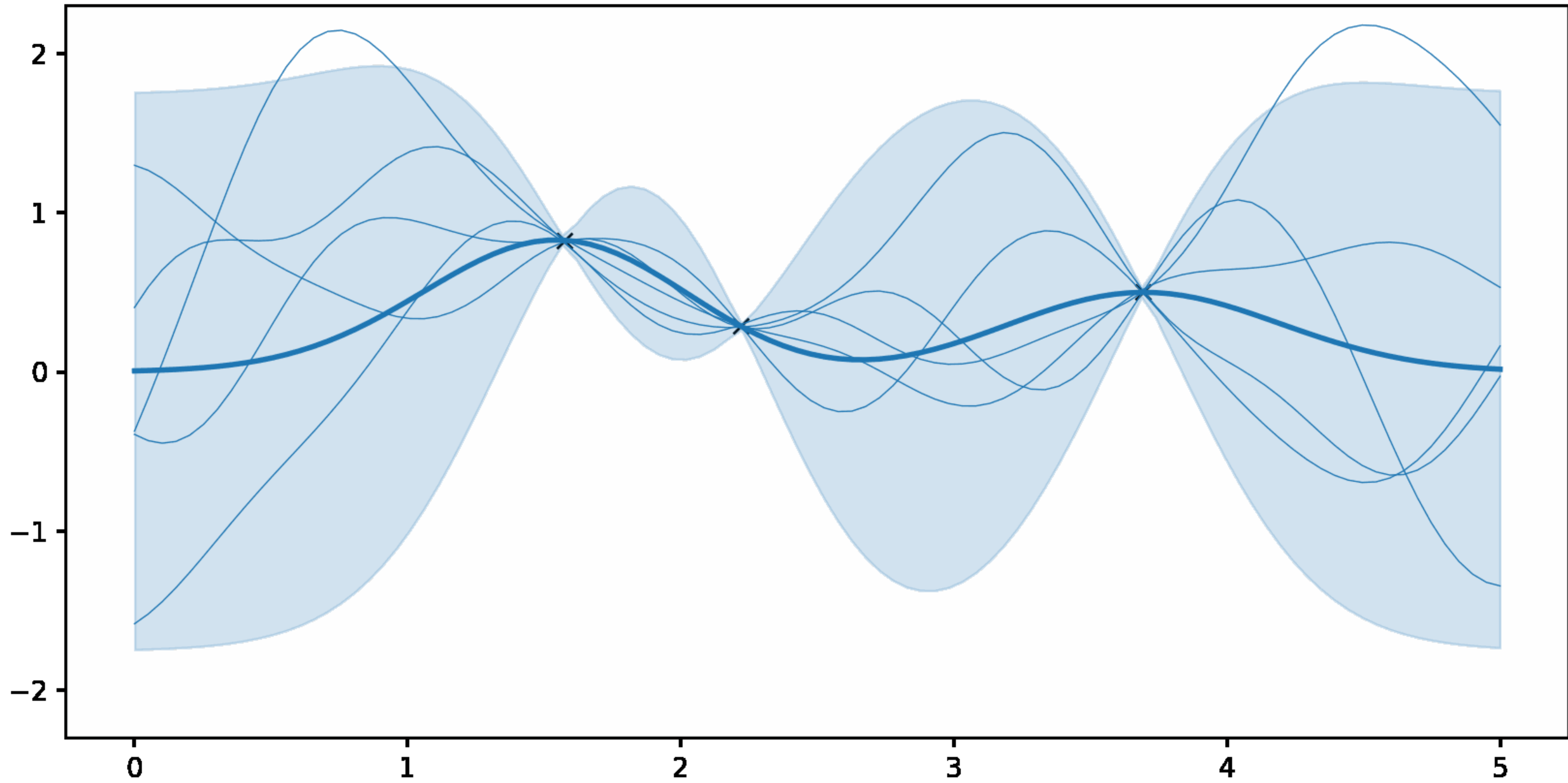
A zero-mean GP  $f : \mathbb{R} \rightarrow \mathbb{R}$

$$p(f|y) = \frac{p(y|f)p(f)}{\int p(y|f)p(f)df}$$



A zero-mean GP  $f: \mathbb{R} \rightarrow \mathbb{R}$

$$p(f|y) = \frac{p(y|f)p(f)}{\int p(y|f)p(f)df}$$



# Function-space vs weight-space view

GP regression is a *kernel method*

$$\hat{f}(x) = \sum_{n=1}^N k(x, x_n) \hat{y}_n$$

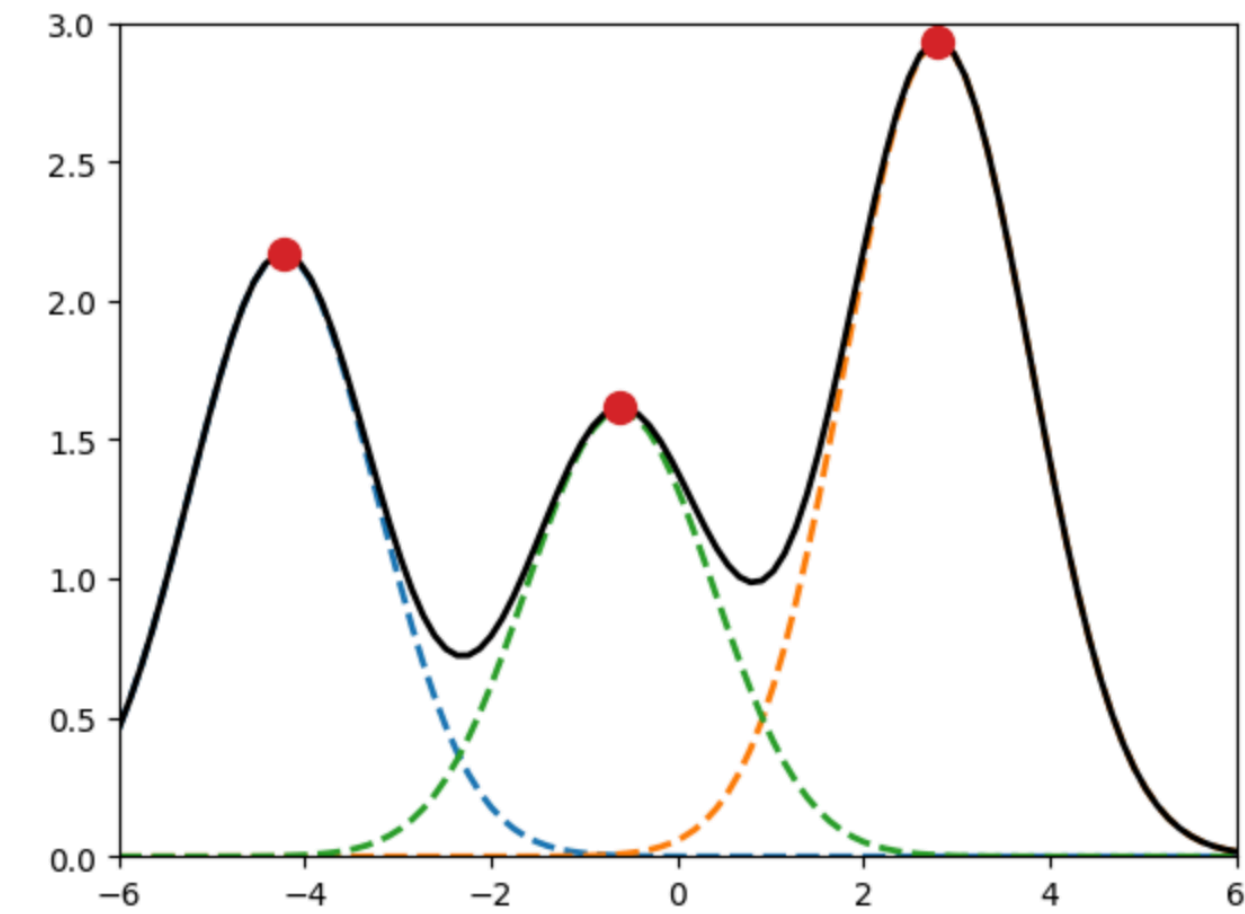
Scales with number of data points  $N$ .

**Weight-space view:**

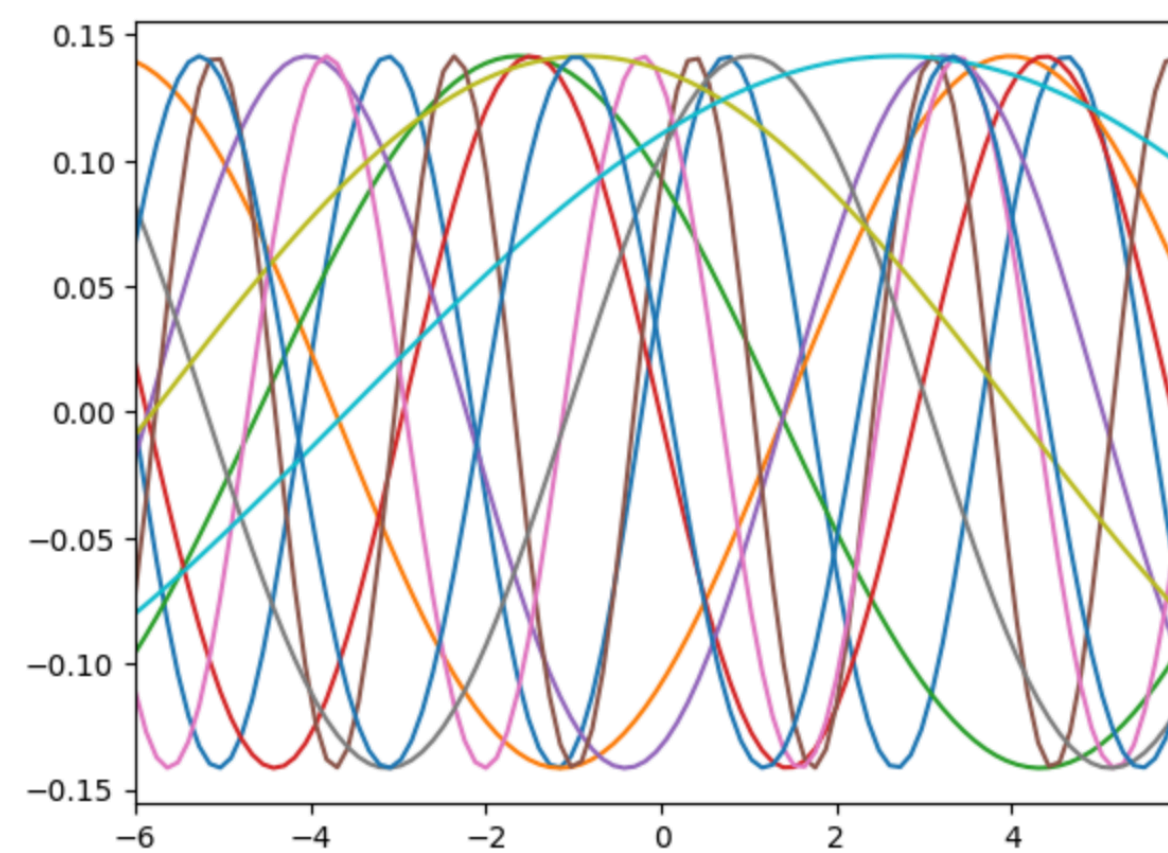
$$\hat{f}(x) \approx \sum_{m=1}^M \theta_m \psi_m(x)$$

where  $k(x, x') \approx \sum \psi_m(x) \psi_m(x')$

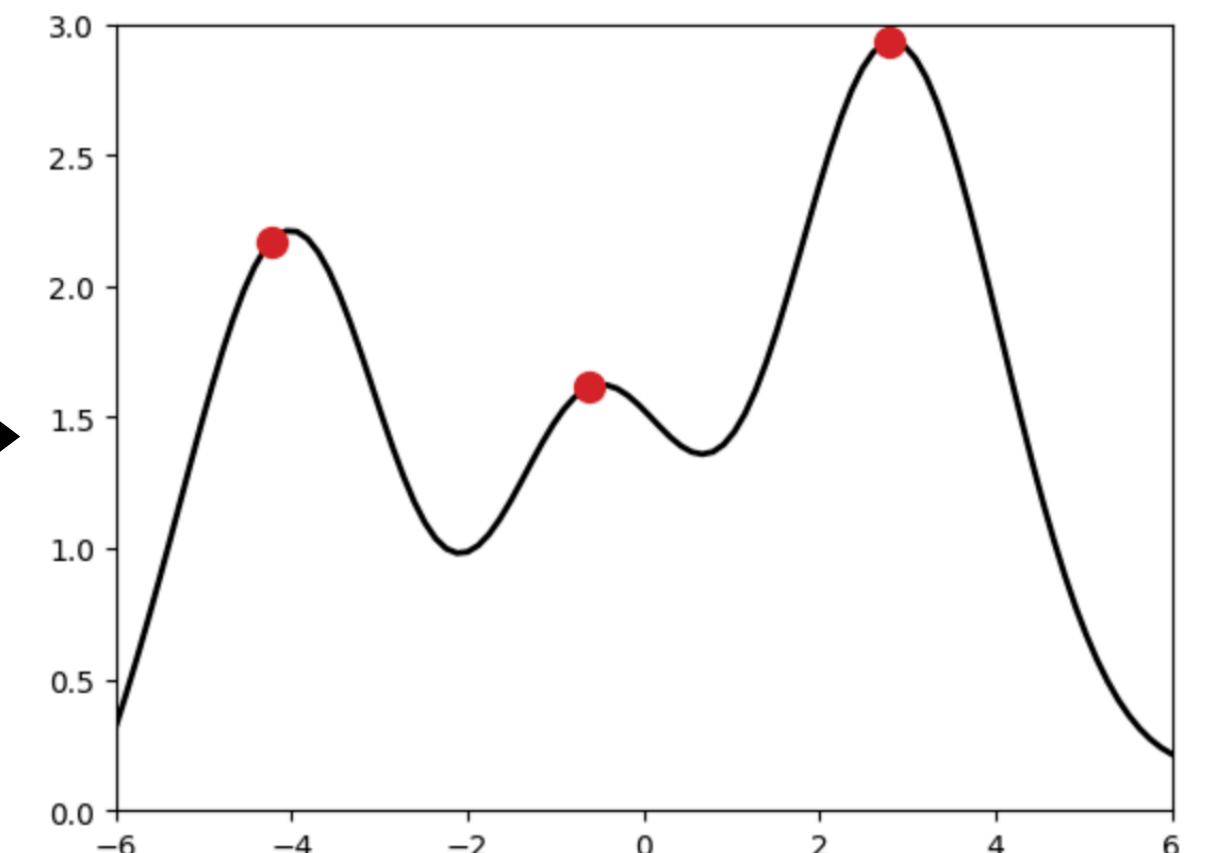
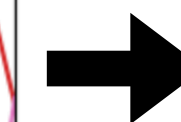
Fit data by learning weights  $\{\theta_m\}_{m=1}^M$ .



Predictive mean with  $k(x, x') = \exp(-|x - x'|^2)$



Basis functions  $\{\psi_m(x)\}_{m=1}^M$



$$\hat{f}(x) = \sum \hat{\theta}_m \psi_m(x)$$



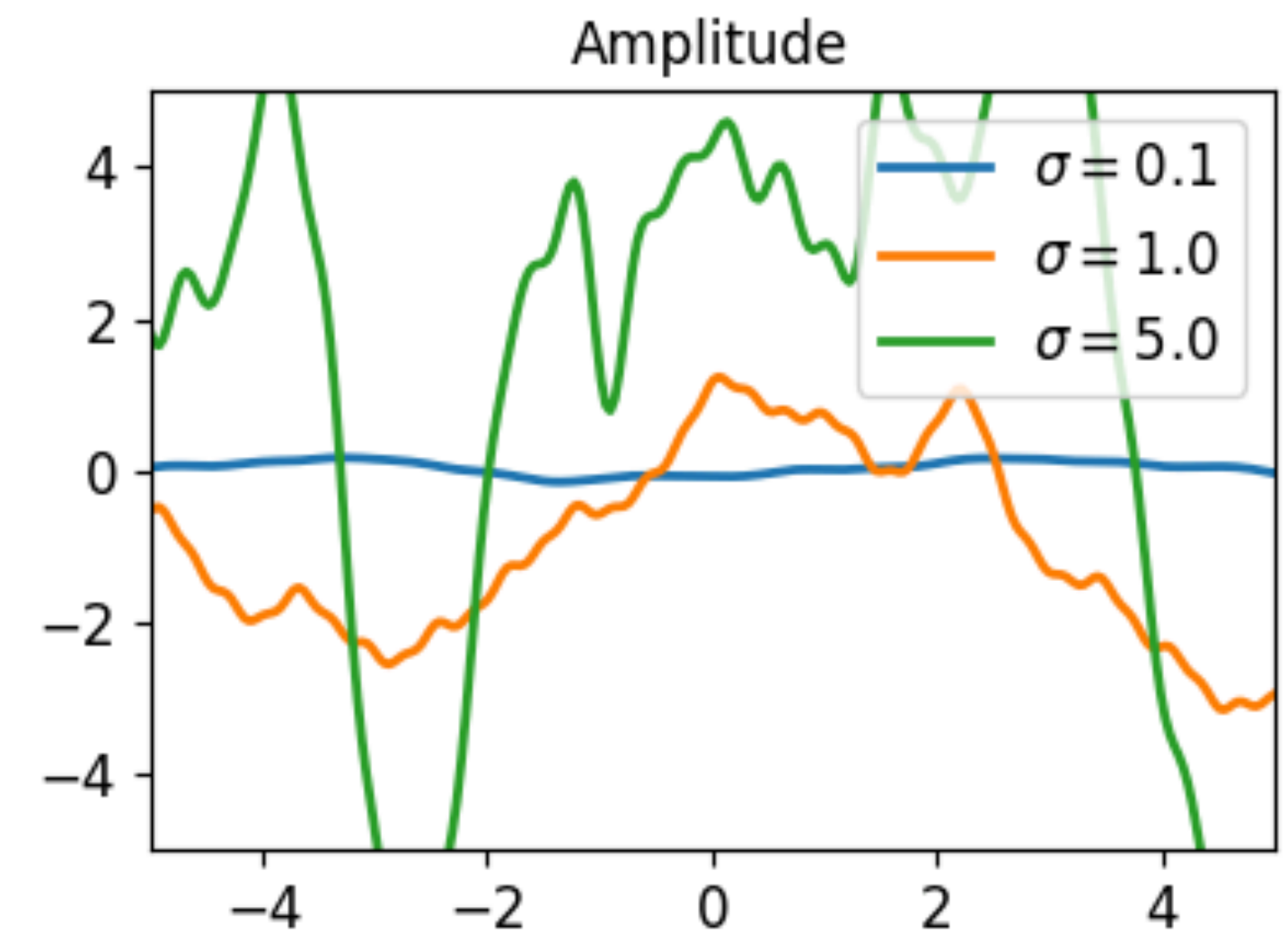
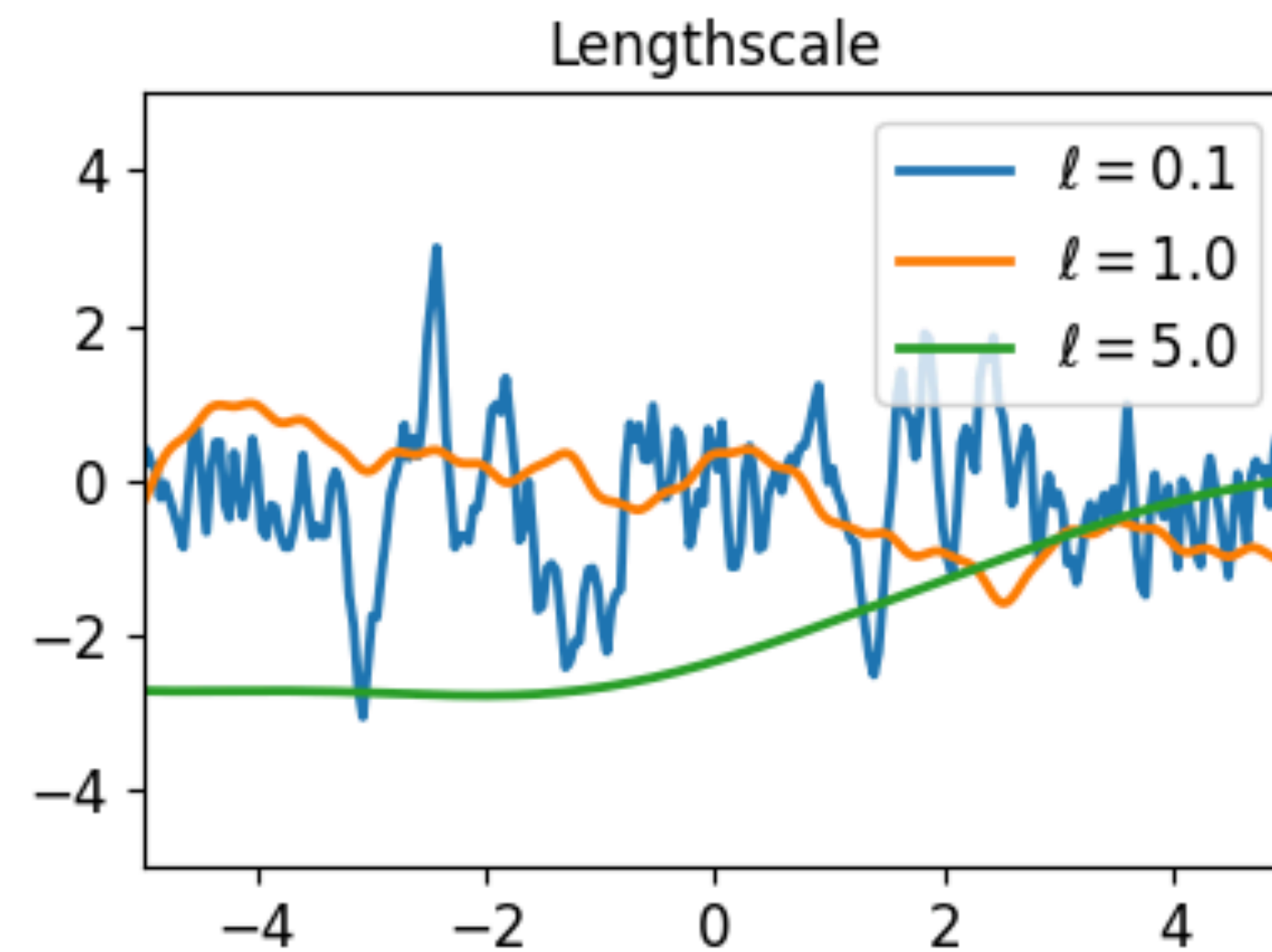
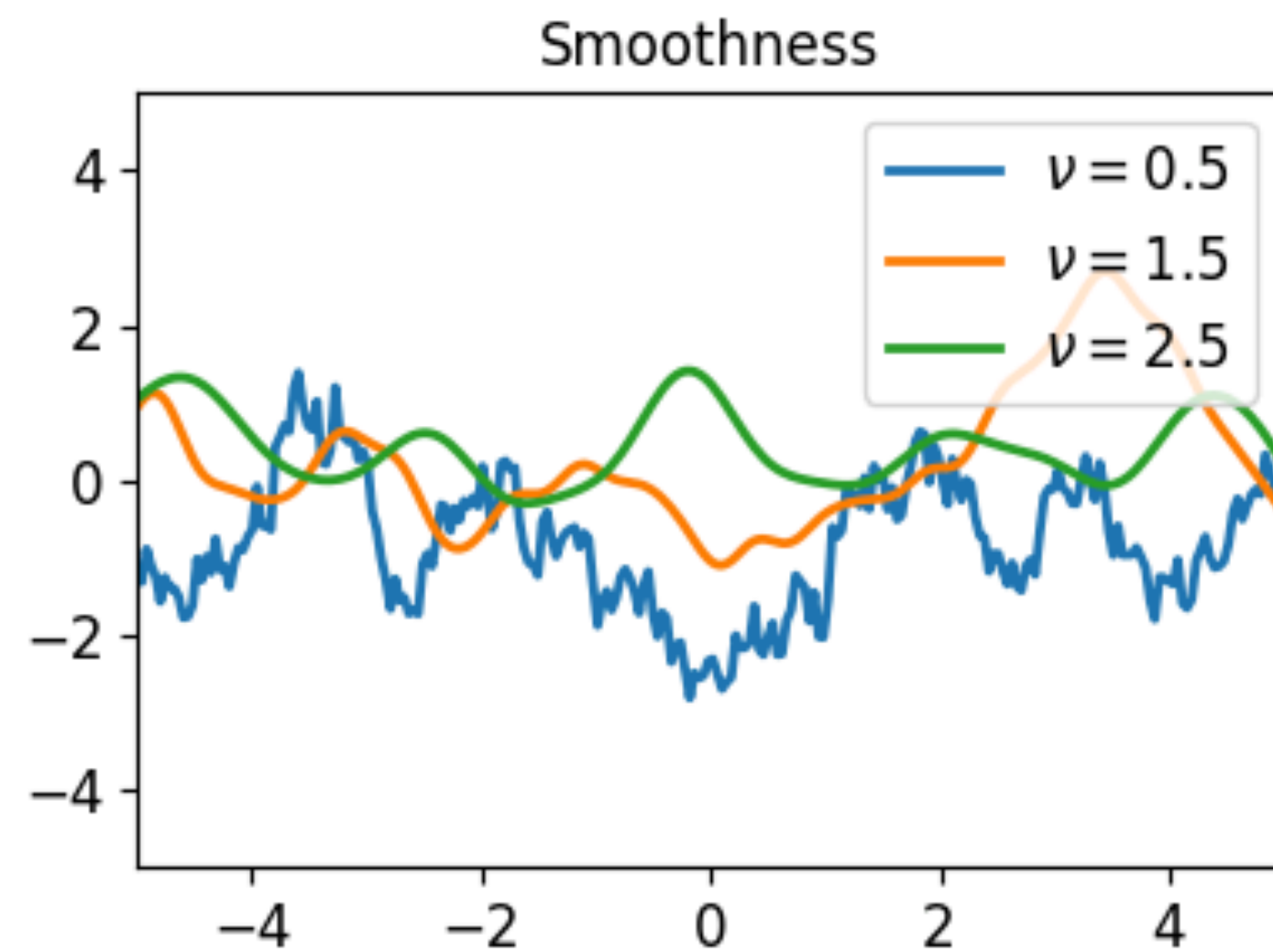
# 0.1. Matérn GPs

# GPs of the Matérn family



Bertil Matérn

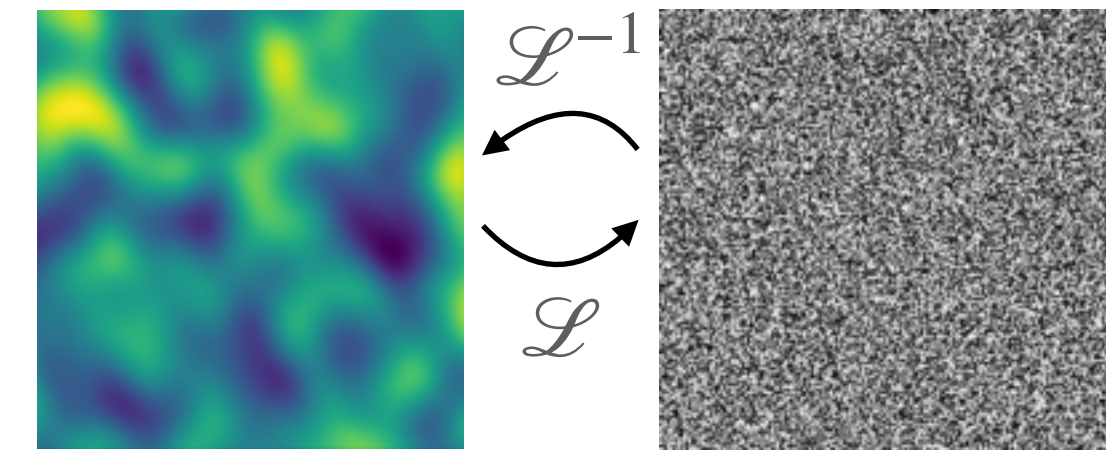
$$k_{\nu, \ell, \sigma}(x, x') = \sigma^2 \frac{2^{1-\nu}}{\Gamma(\nu)} \left( \sqrt{2\nu} \frac{|x - x'|}{\ell} \right)^\nu K_\nu \left( \sqrt{2\nu} \frac{|x - x'|}{\ell} \right)$$



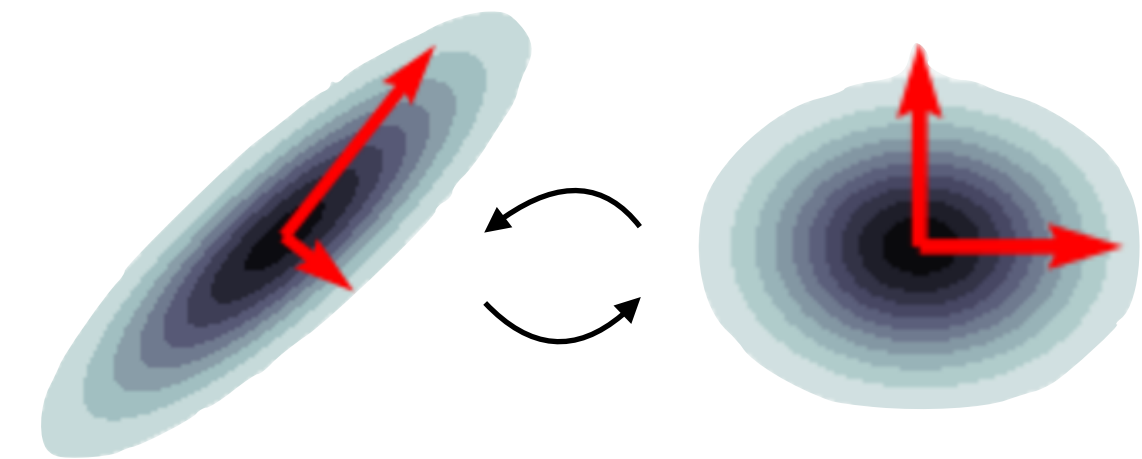
# SPDE reformulation of Matérn GPs

Matérn GPs can also be derived as a solution to the stochastic PDE:

$$\underbrace{\left( \frac{2\nu}{\ell^2} - \Delta \right)^{\frac{\nu+d/2}{2}}}_{=: \mathcal{L}} f = \mathcal{W}_\sigma$$



This is a “white noise” on Sobolev spaces over  $\mathbb{R}^d$



$$H^{\nu+d/2}(\mathbb{R}^d) := \left\{ f \in L^2(\mathbb{R}^d) : \int_{\mathbb{R}^d} \left( 1 + |\omega|^2 \right)^{\nu+d/2} |\hat{f}(\omega)|^2 d\omega < \infty \right\}.$$

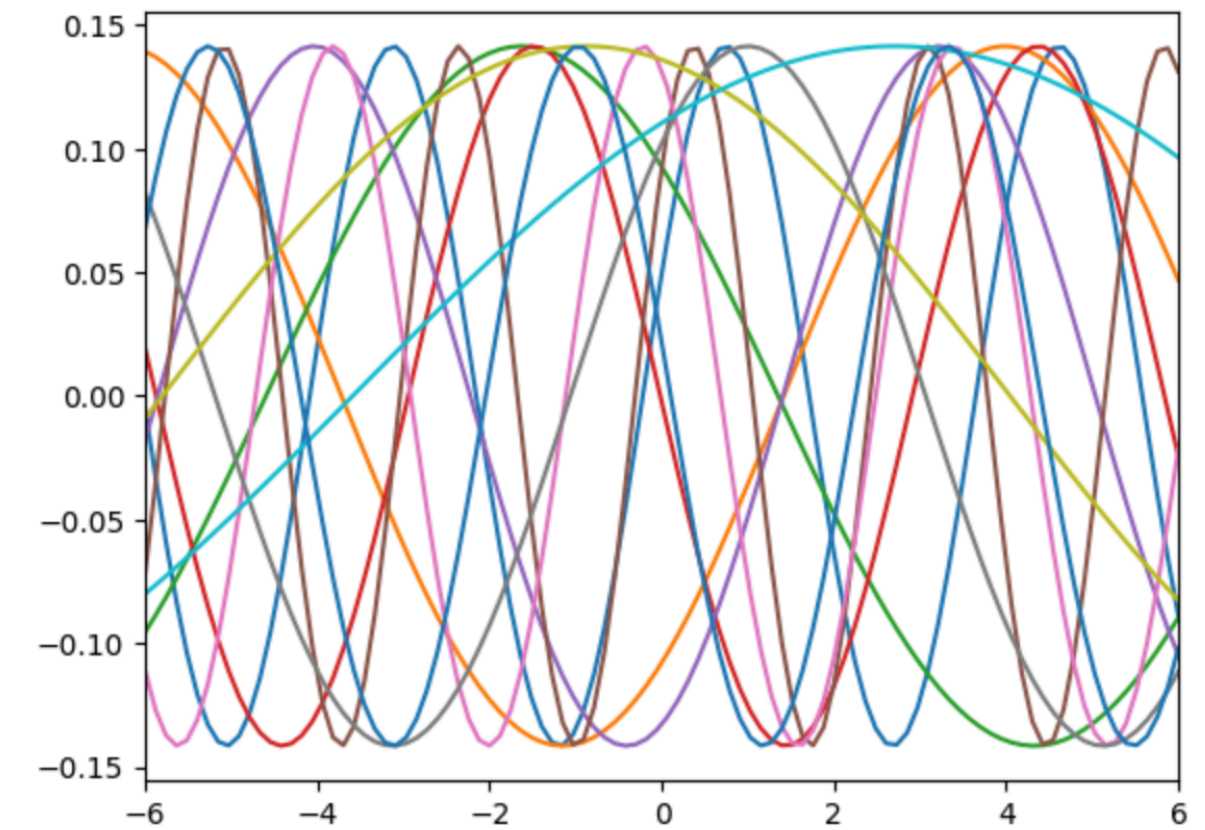
# Random feature expansion of Matérn GPs

The Matérn kernel over  $\mathbb{R}^d$  can also be expressed as

$$k_{\nu, \ell, \sigma}(x, x') = 2\sigma^2 \mathbb{E}_{\omega, b} [\cos(\omega^\top x + b) \cos(\omega^\top x' + b)], \quad \omega \sim t_{2\nu}(0, \ell^{-2}),$$

$$\approx \sum_{m=1}^M \sqrt{\frac{2\sigma^2}{M}} \cos(\omega_m^\top x + b_m) \sqrt{\frac{2\sigma^2}{M}} \cos(\omega_m^\top x' + b_m),$$

$$\omega_m \sim t_{2\nu}(0, \ell^{-2}), \quad b_m \sim U([0, 2\pi]).$$

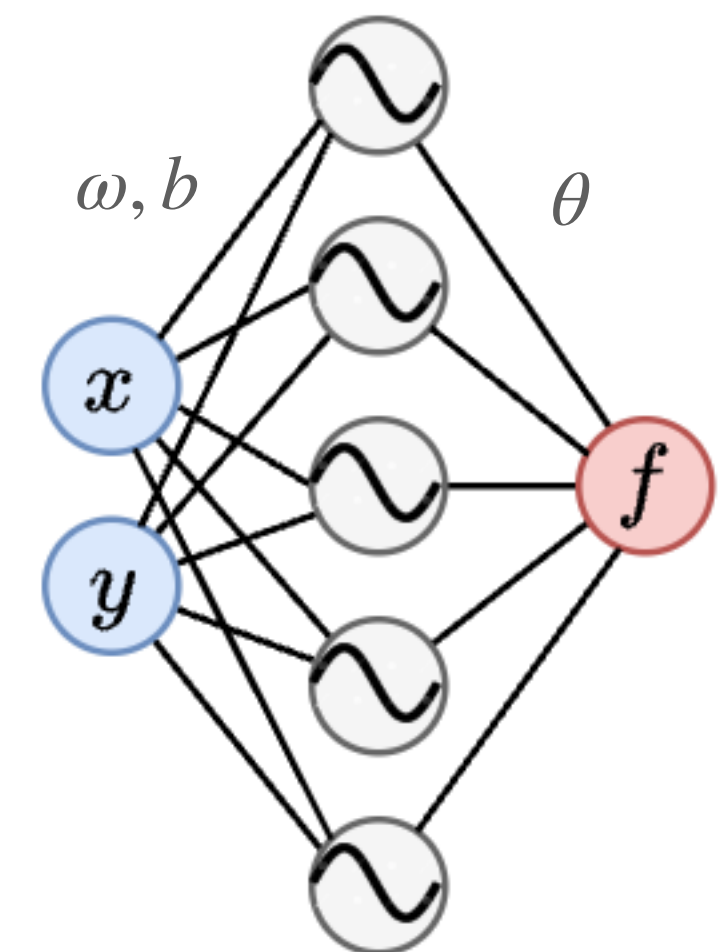


This gives us the weight-space representation of Matérn GPs\*

$$f(x) \approx \sum_{m=1}^M \theta_m \psi_m(x), \quad \text{where} \quad \psi_m(x) = \sqrt{\frac{2\sigma^2}{M}} \cos(\omega_m^\top x + b_m)$$

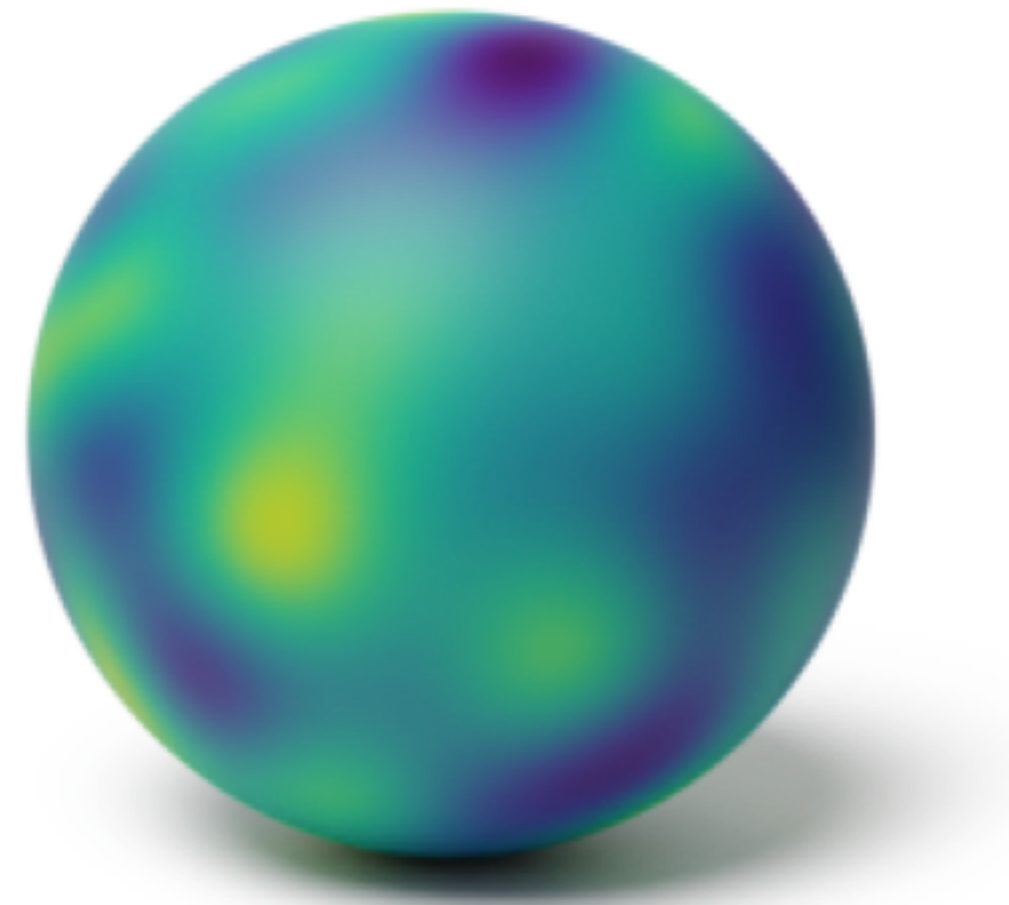
$$\text{and} \quad \theta_m \sim \mathcal{N}(0, 1).$$

Random features!



\*Rahimi et al. "Random features for large-scale kernel machines." *NeurIPS* 2007.

# 1. Riemannian Matérn GPs



# A no-go result

Recall the Matérn kernel on  $\mathbb{R}^d$

$$k_{\nu, \ell, \sigma}(x, x') = \sigma^2 \frac{2^{1-\nu}}{\Gamma(\nu)} \left( \sqrt{2\nu} \frac{|x - x'|}{\ell} \right)^\nu K_\nu \left( \sqrt{2\nu} \frac{|x - x'|}{\ell} \right)$$

On manifolds, can we just replace  $|x - x'|$  by the geodesic distance?

## No-go Theorem\*:

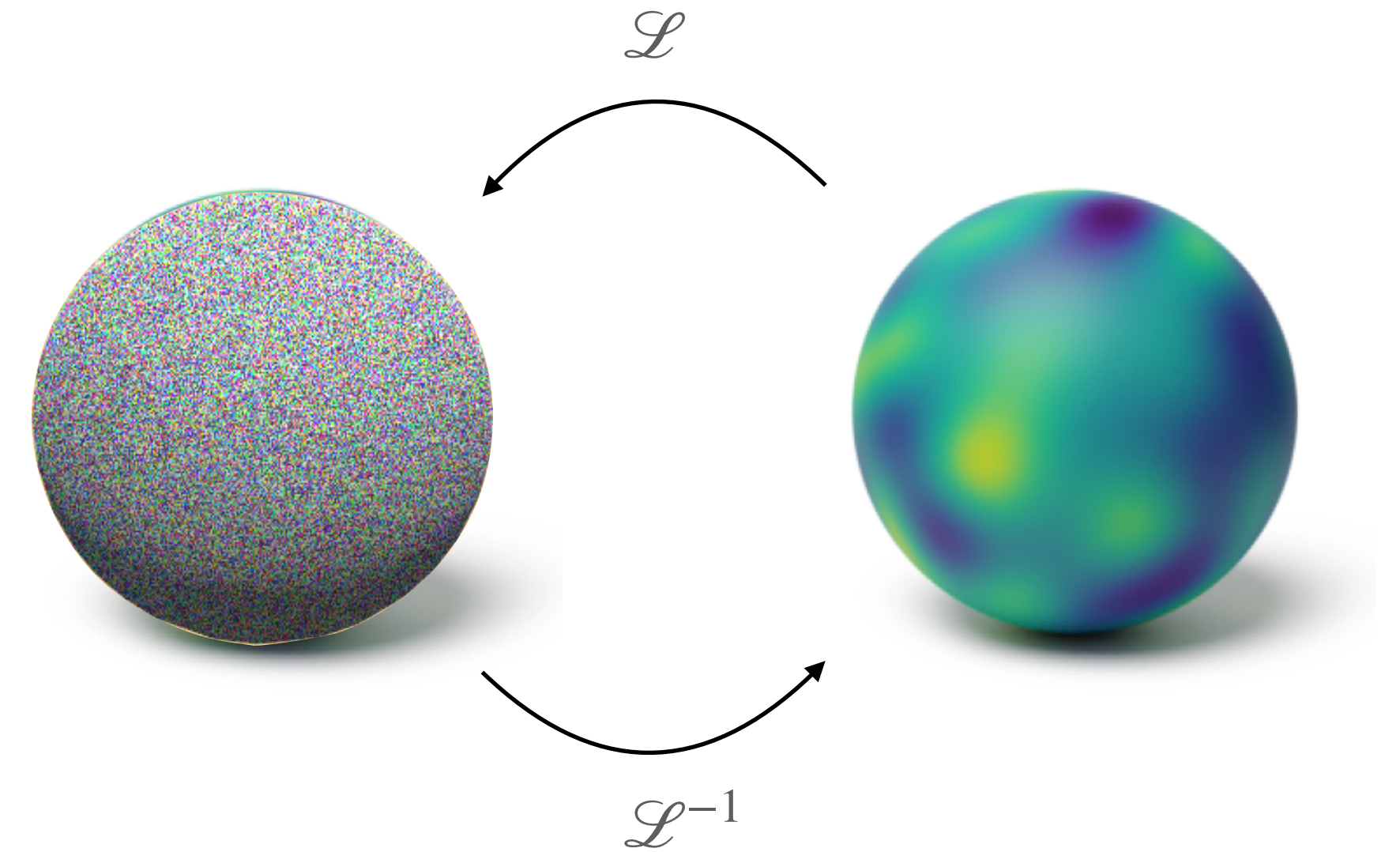
The resulting kernel is positive semidefinite if and only if the manifold is flat.

\*Feragen et al.. "Geodesic exponential kernels: When curvature and linearity conflict." *CVPR*. 2015.

# SPDE Approach

Recall the SPDE formulation of Matérn GP:

$$\underbrace{\left( \frac{2\nu}{\ell^2} - \Delta \right)^{\frac{\nu + d/2}{2}}}_{=: \mathcal{L}} f = \mathcal{W}_\sigma$$



Extend to Riemannian manifolds by using the **Laplace-Beltrami operator  $\Delta$** ?\*

\*Lindgren et al. "An explicit link between Gaussian fields and Gaussian Markov random fields: the stochastic partial differential equation approach." *J. Royal. Stat. Soc. B.* 2011.

# Kernel construction

Let  $\{(\lambda_n, \phi_n)\}_{n=0}^{\infty}$  be eigendecomposition of  $-\Delta$  over a compact Riemannian manifold

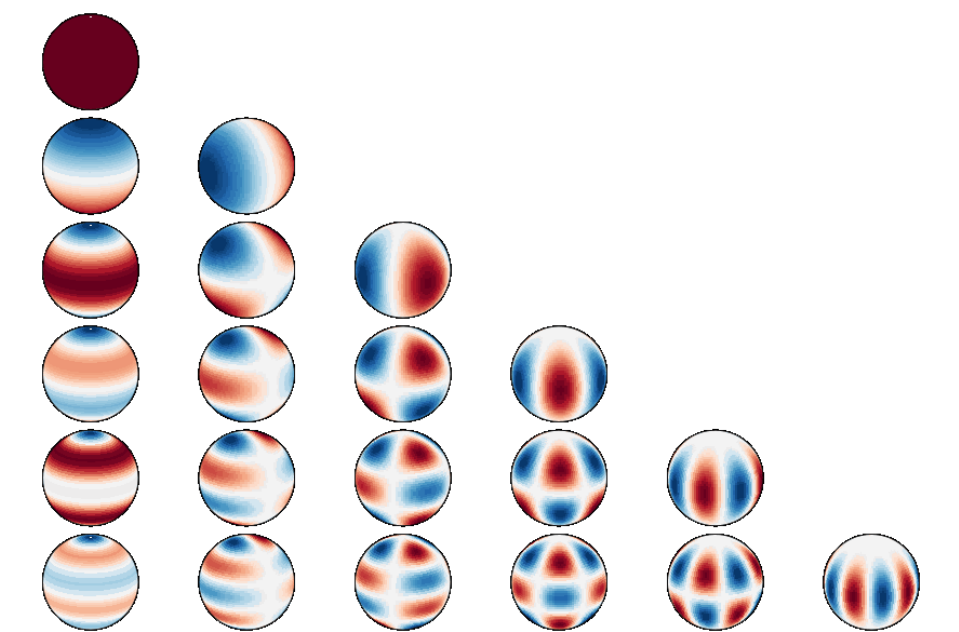
- On  $\mathbb{T}^d$ , we have  $\lambda_n = n^2$  and  $\phi_n(x) = \{\sin(nx), \cos(nx)\}$
- On  $\mathbb{S}^2$ , we have  $\lambda_n = n(n+1)$  and  $\phi_n(x) = \{Y_n^1(x), \dots, Y_n^{2n+1}(x)\}$

**Theorem:\***

$f \sim GP(0, k(\cdot, \cdot))$ , where

$$k(x, x') = \frac{\sigma^2}{C_{\nu, \ell}} \sum_{n=0}^{\infty} \left( \frac{2\nu}{\ell^2} + \lambda_n \right)^{-\nu-d/2} \phi_n(x) \phi_n(x')$$

is a solution to the SPDE  $(2\nu/\ell^2 - \Delta)^{\frac{\nu+d/2}{2}} f = \mathcal{W}_\sigma$





# Concrete expressions\*

Matérn- $\nu$  on  $\mathbb{R}^d$ :

$$k_{\nu, \ell, \sigma}(x, x') = \sigma^2 \frac{2^{1-\nu}}{\Gamma(\nu)} \left( \sqrt{2\nu} \frac{|x - x'|}{\ell} \right)^\nu K_\nu \left( \sqrt{2\nu} \frac{|x - x'|}{\ell} \right)$$

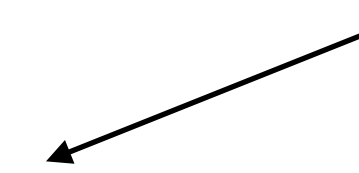
Matérn-1/2 on  $\mathbb{T}^1$ :

$$k_{1/2, \ell, \sigma}(x, x') = \frac{\sigma^2}{\cosh(1/2\ell)} \cosh \left( \frac{|x - x' - 1/2|}{\ell} \right)$$

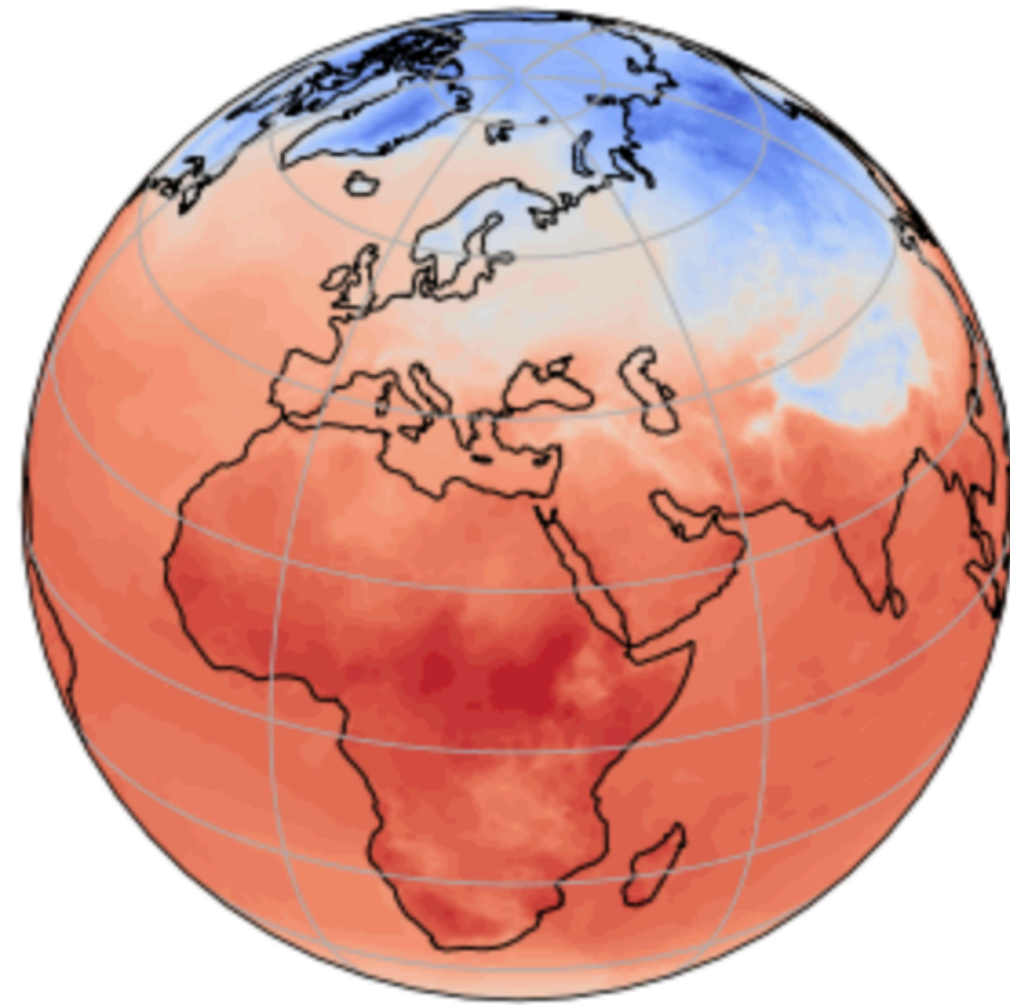
Matérn- $\nu$  on  $S^2$ :

$$k_{\nu, \ell, \sigma}(x, x') = \sigma^2 \sum_{n=0}^{\infty} c_n \rho_\nu(n) \mathcal{G}_n^{1/2}(\cos(\langle x, x' \rangle))$$

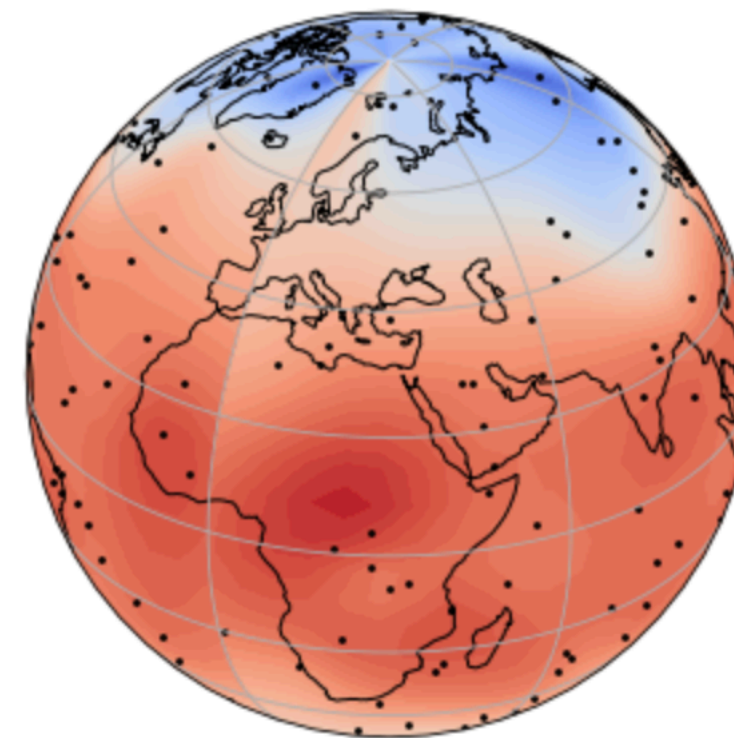
Gegenbauer polynomial



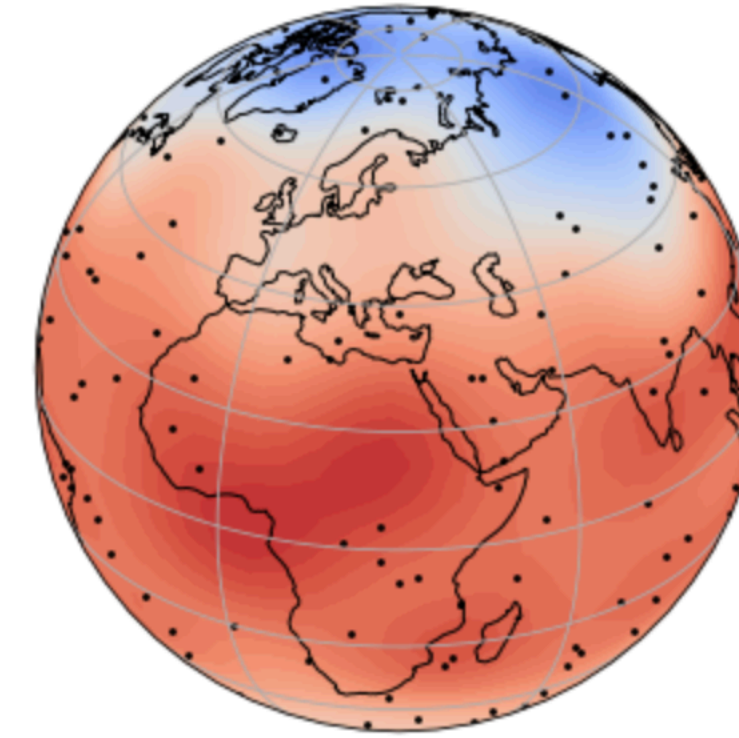
# Global temperature interpolation



2m temperature from ERA5



Euclidean Matérn GP



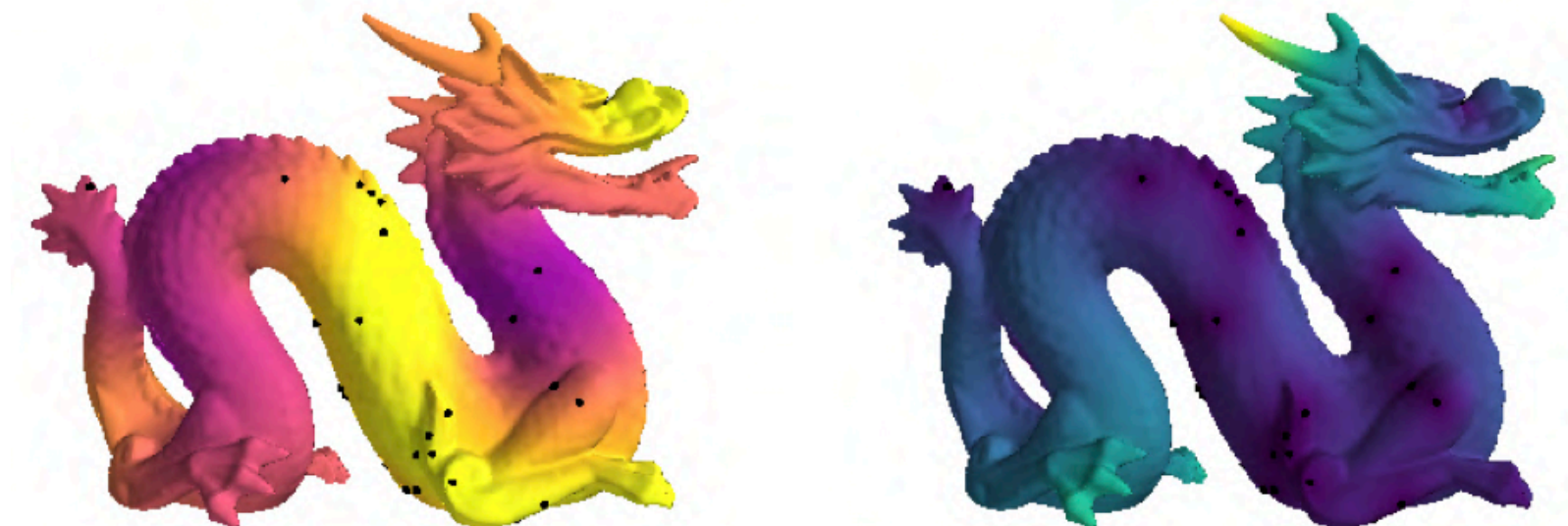
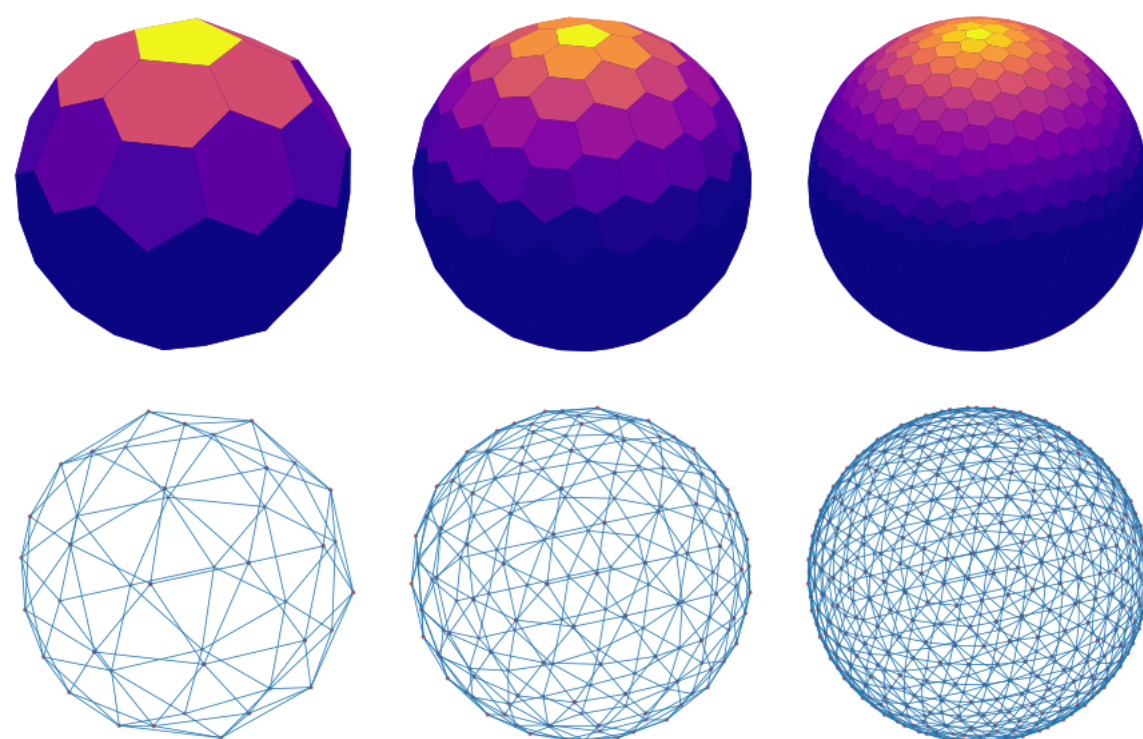
Spherical Matérn GP

# Graph approximations

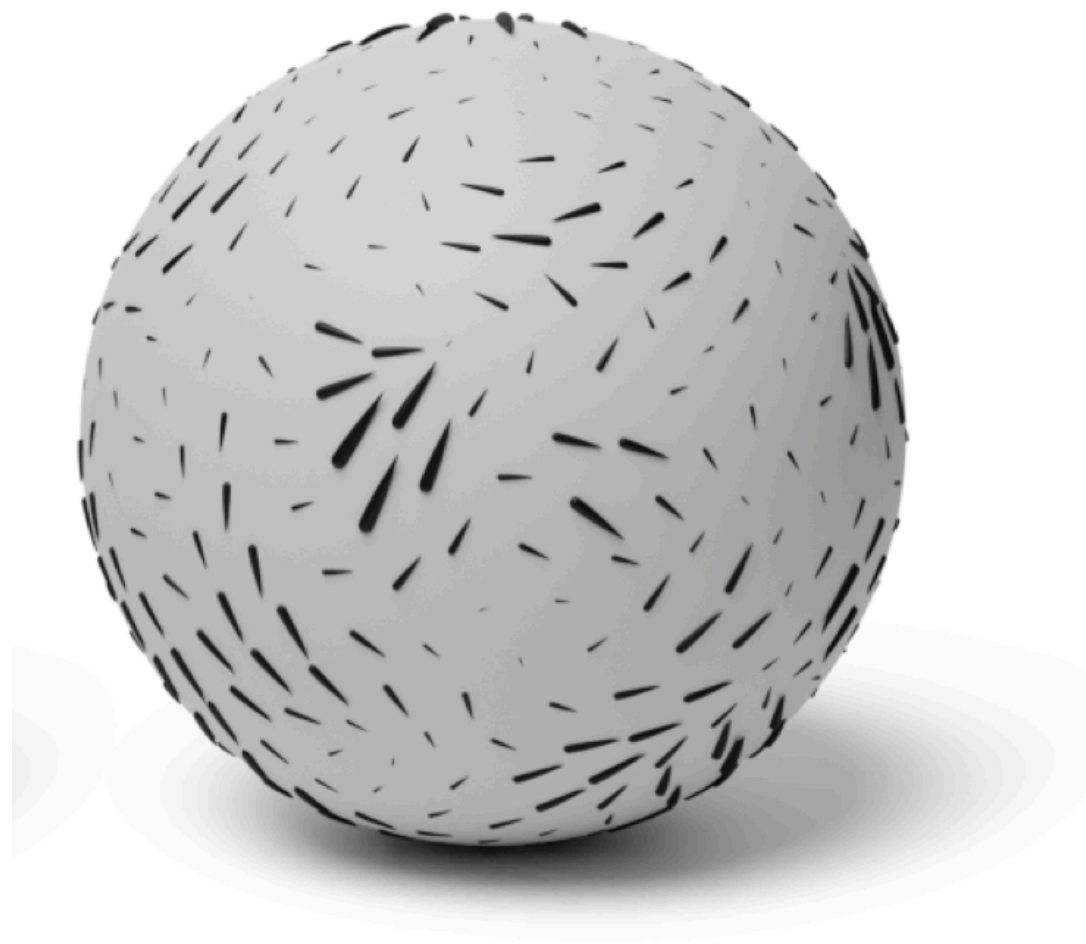
Recall expression for Riemannian Matérn kernel:

$$k(x, x') = \frac{\sigma^2}{C_{\nu, \ell}} \sum_{n=0}^{\infty} \left( \frac{2\nu}{\ell^2} + \lambda_n \right)^{-\nu - d/2} \phi_n(x) \phi_n(x')$$

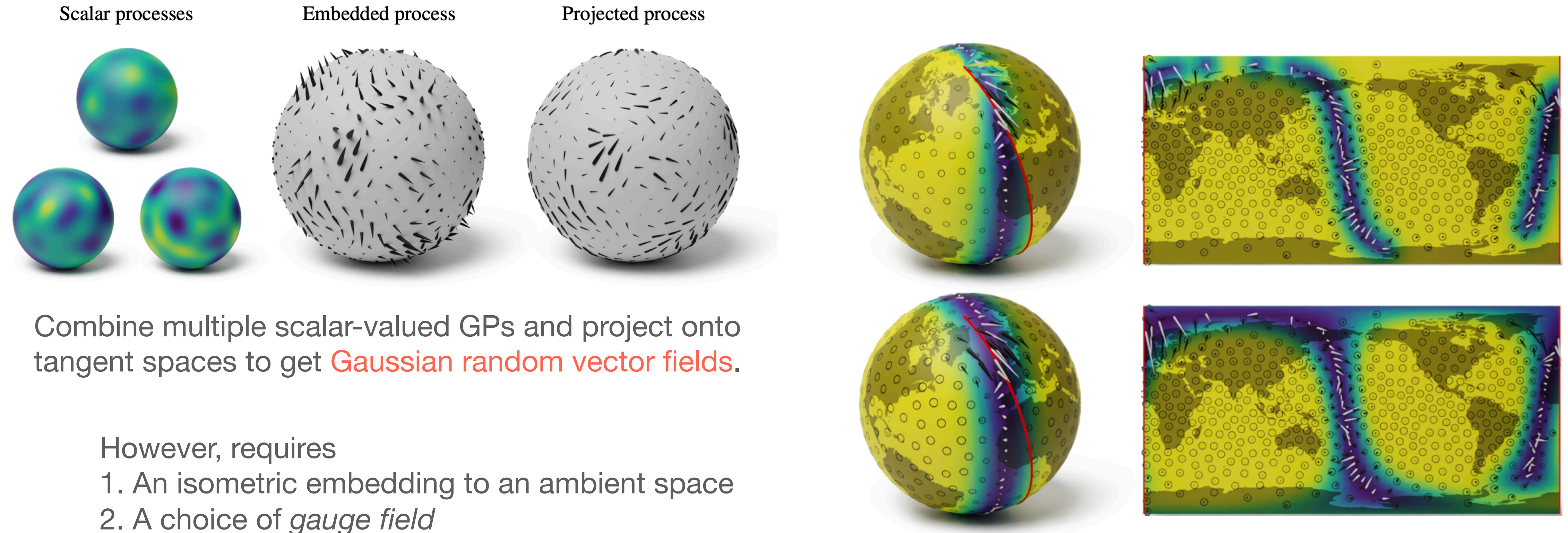
We can use  $\{(\lambda_n, \phi_n)\}_{n=0}^{\infty}$  of the *graph Laplacian* instead!



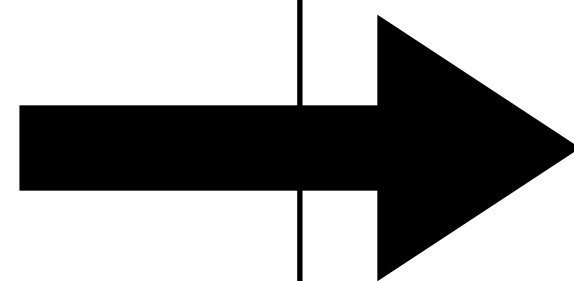
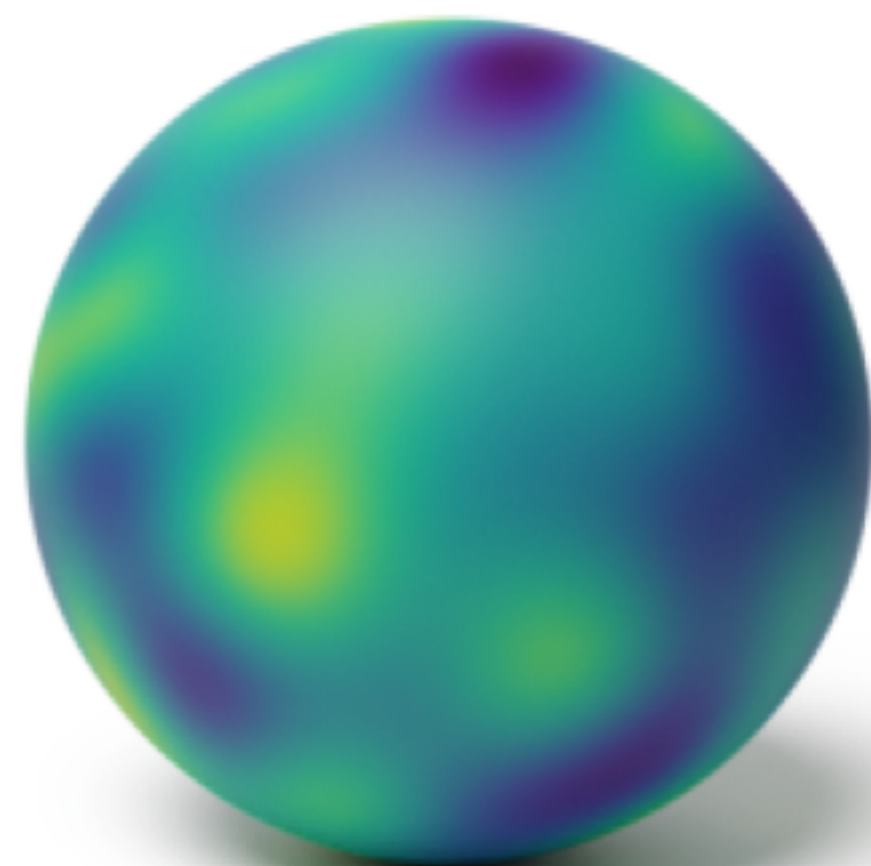
## 2. Matérn Gaussian vector fields



# Gauge-equivariant vector GP



# Manifolds

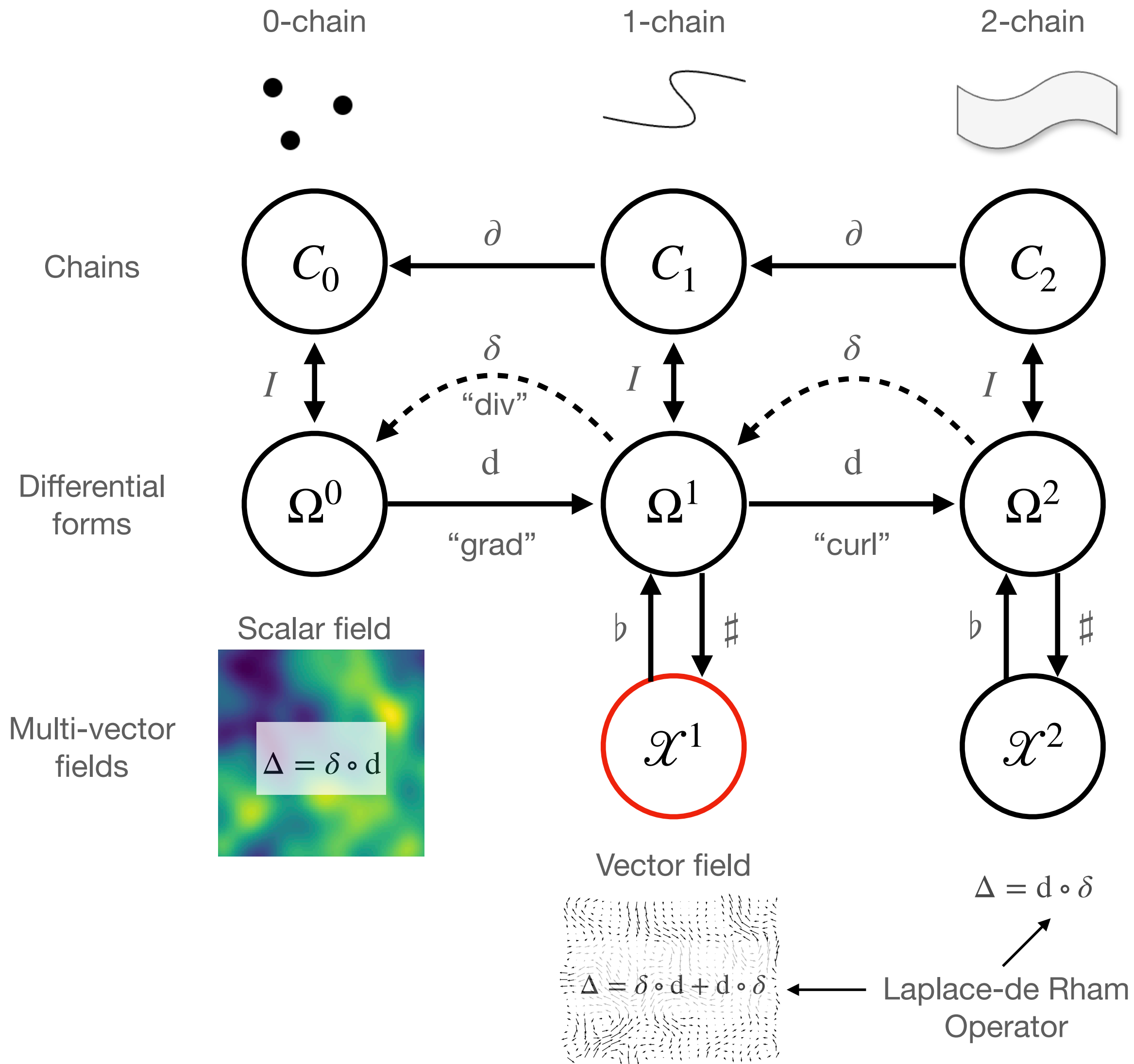


# Graphs

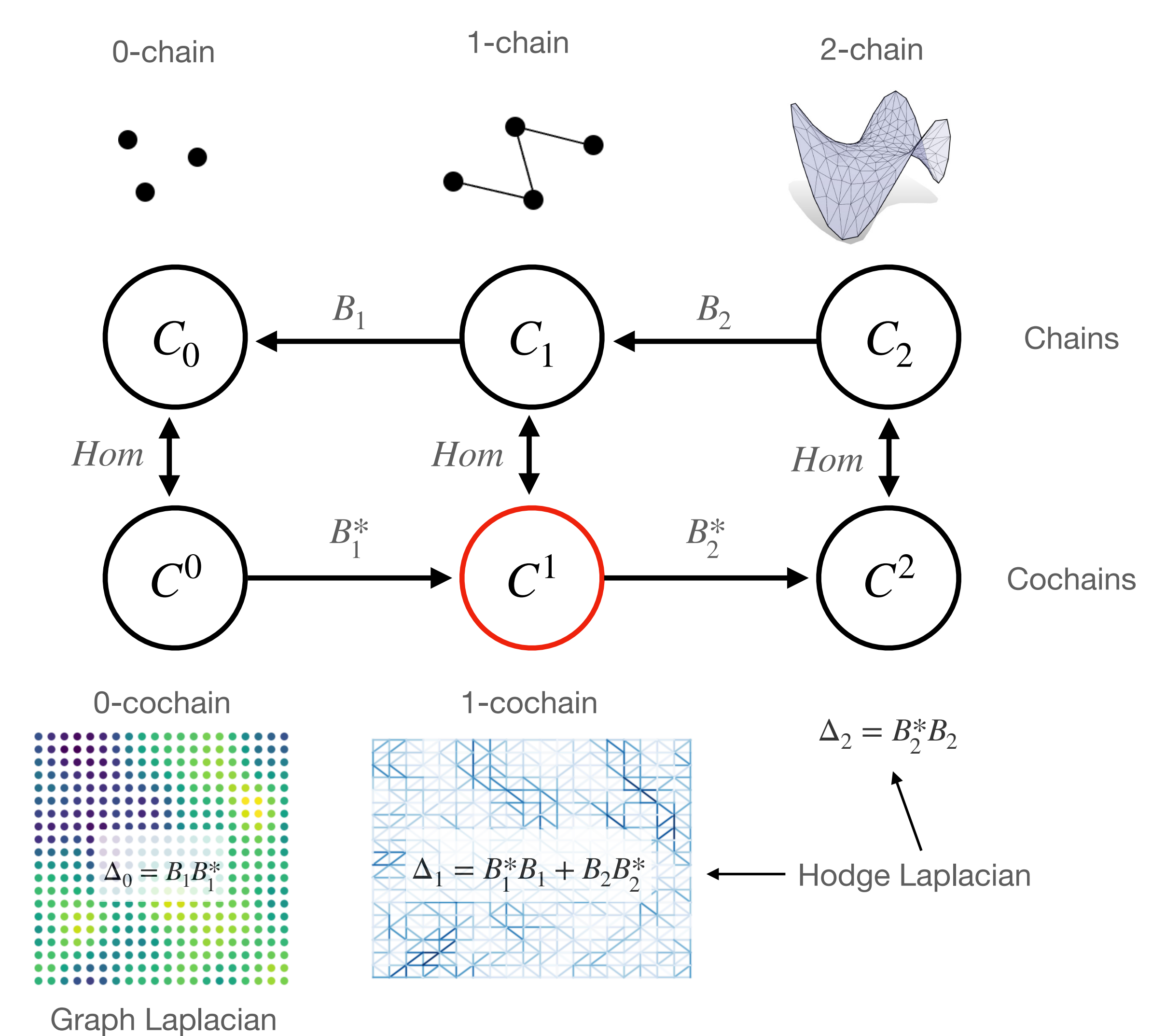


# Chasin' the gram: some homological algebra

Continuous



Discrete

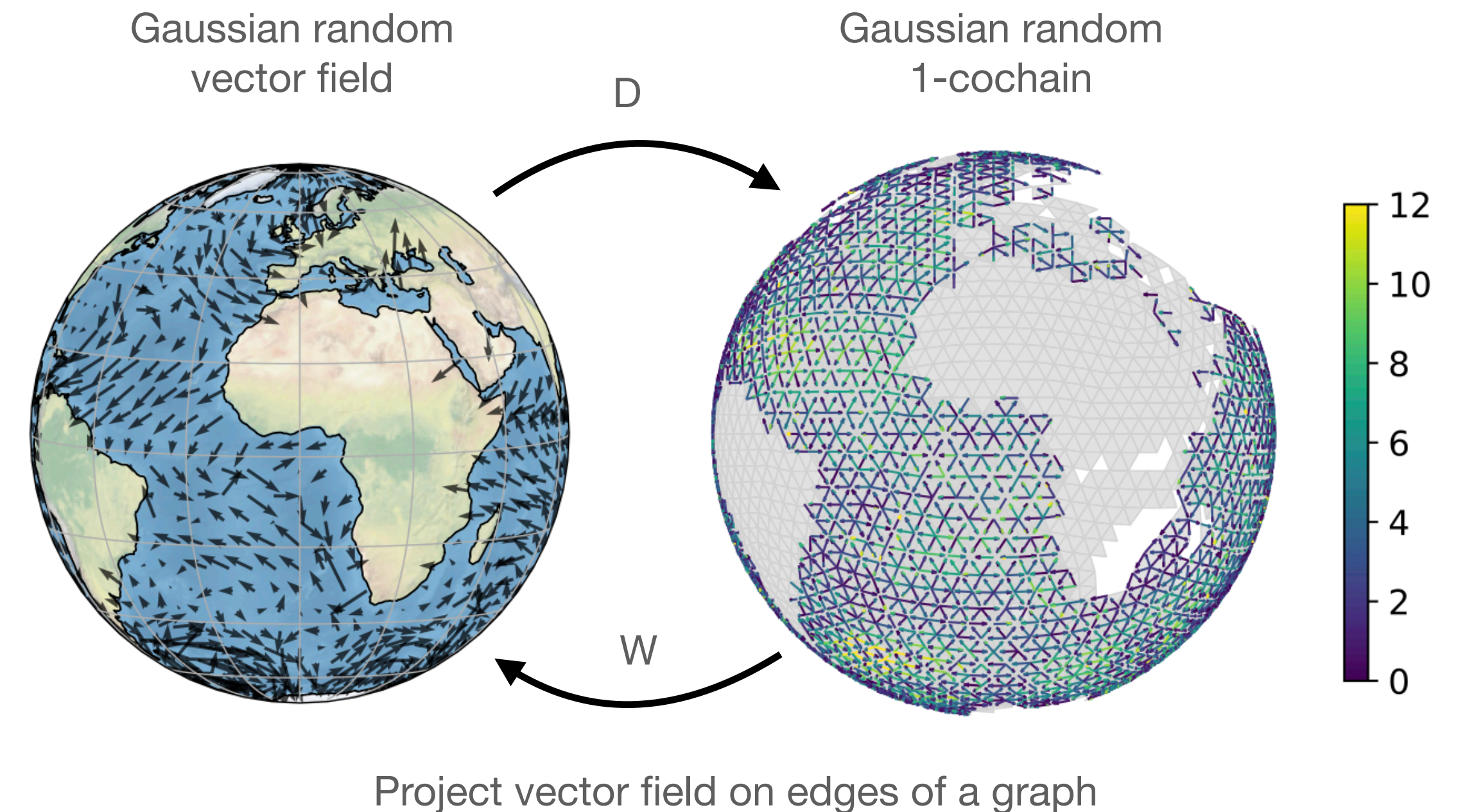


# Gaussian random cochains

We define a **Gaussian random  $k$ -cochain** as a random group homomorphism

$$f: C_k \rightarrow \mathbb{R},$$

such that  $f(c)$  is Gaussian for all  $c \in C_k$ .





# Matérn random cochain

A Gaussian random  $k$ -cochain  $f : C_k \rightarrow \mathbb{R}$  is of the **Matérn class** if it satisfies

$$\left( \frac{2\nu}{\ell^2} + \Delta_k \right)^{\frac{\nu + d/2}{2}} f = \mathcal{W}_\sigma$$

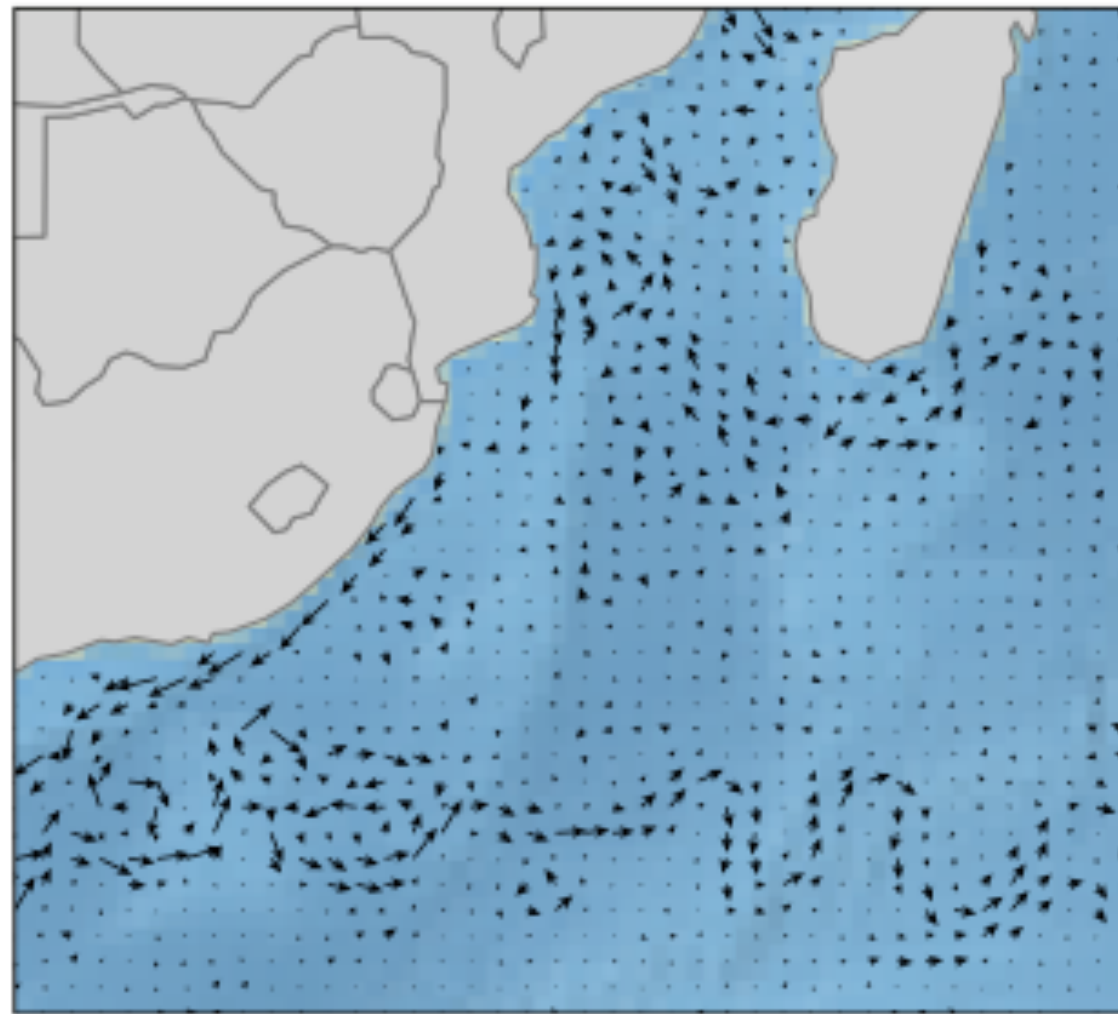
Kernel has the numerical representation

$$\mathbf{K} = \sigma^2 \mathbf{U} \left( \frac{2\nu}{\ell^2} \mathbf{I} + \mathbf{\Lambda} \right)^{-\nu - d/2} \mathbf{U}^\top,$$

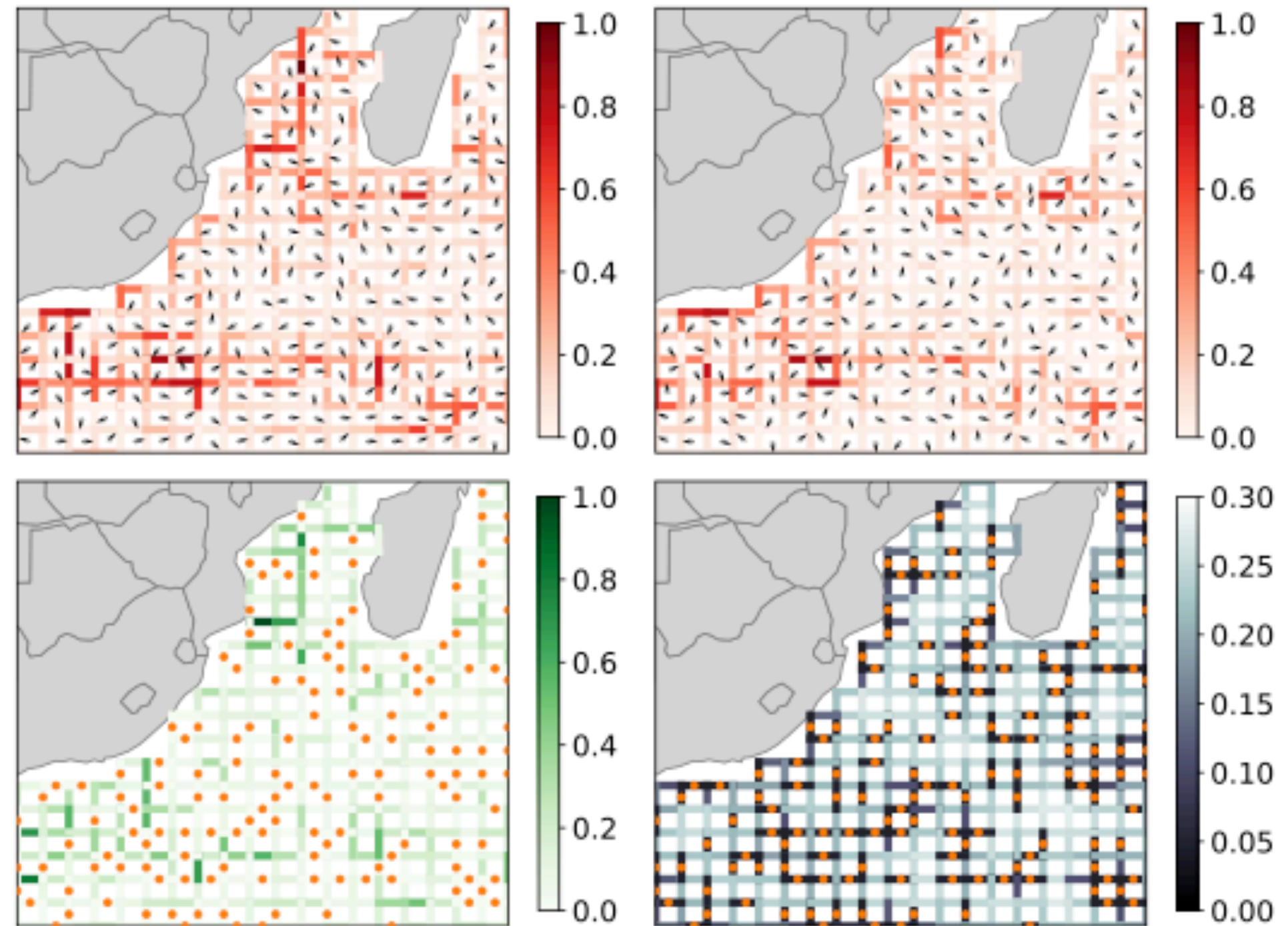
where  $\Delta_k = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^\top$  is the eigen-decomposition of the Hodge Laplacian.

$$k(x, x') = \sigma^2 \sum_{n=0}^{\infty} \left( \frac{2\nu}{\ell^2} + \lambda_n \right)^{-\nu - d/2} \phi_n(x) \phi_n(x')$$

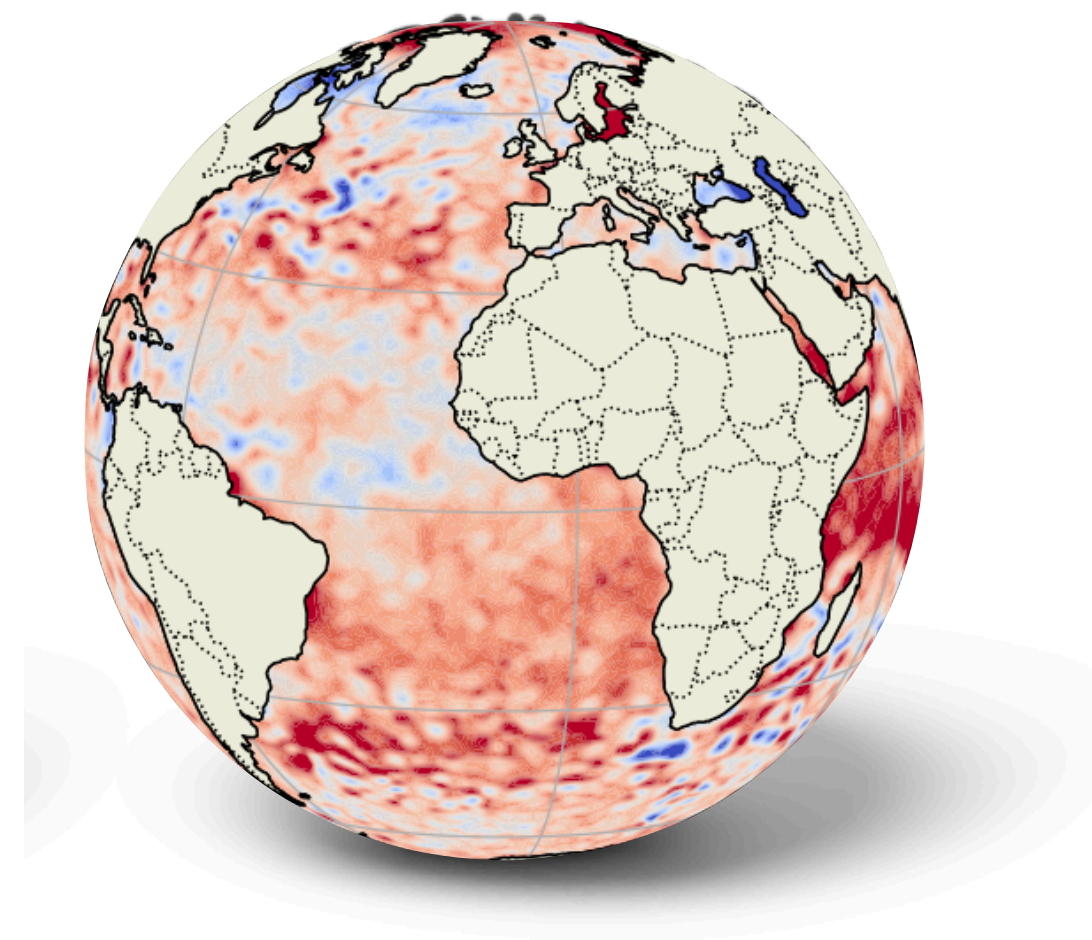
# Ocean current interpolation



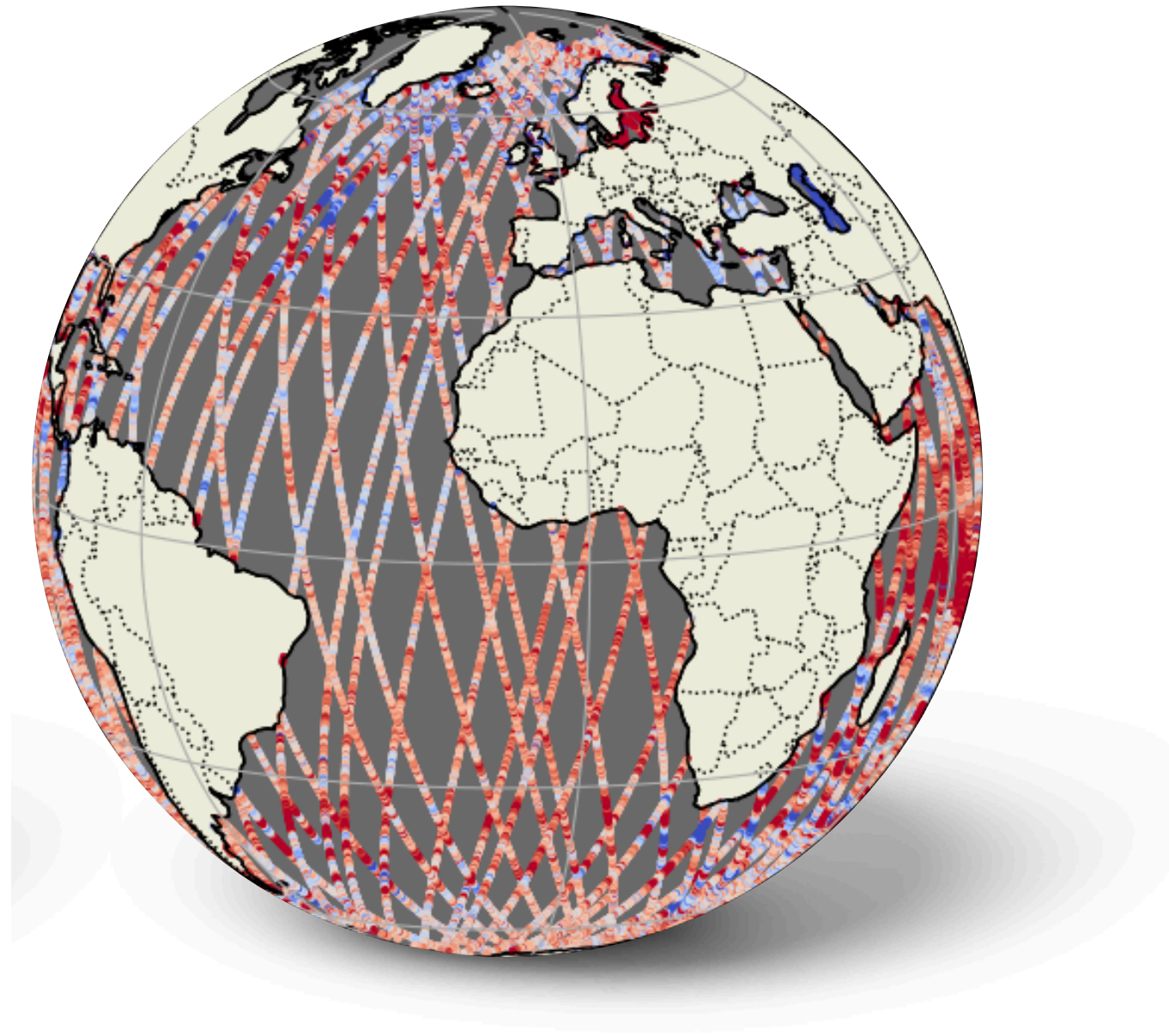
(a) Geostrophic current



# 3. Deep Random Features



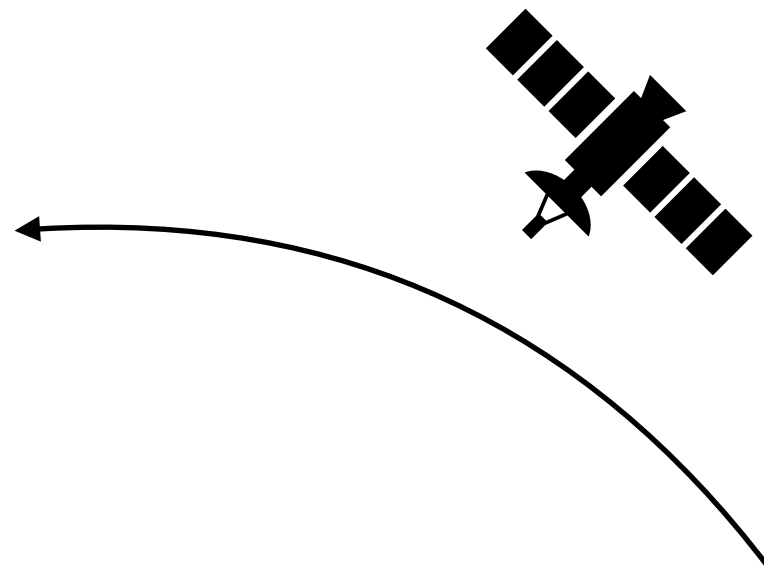
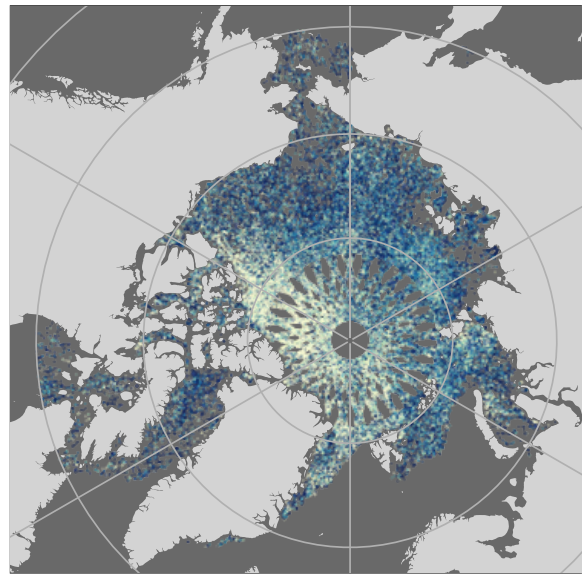
# Limitations of Gaussian processes



Sea-level observations from Sentinel 3A and 3B  
8,094,569 data points

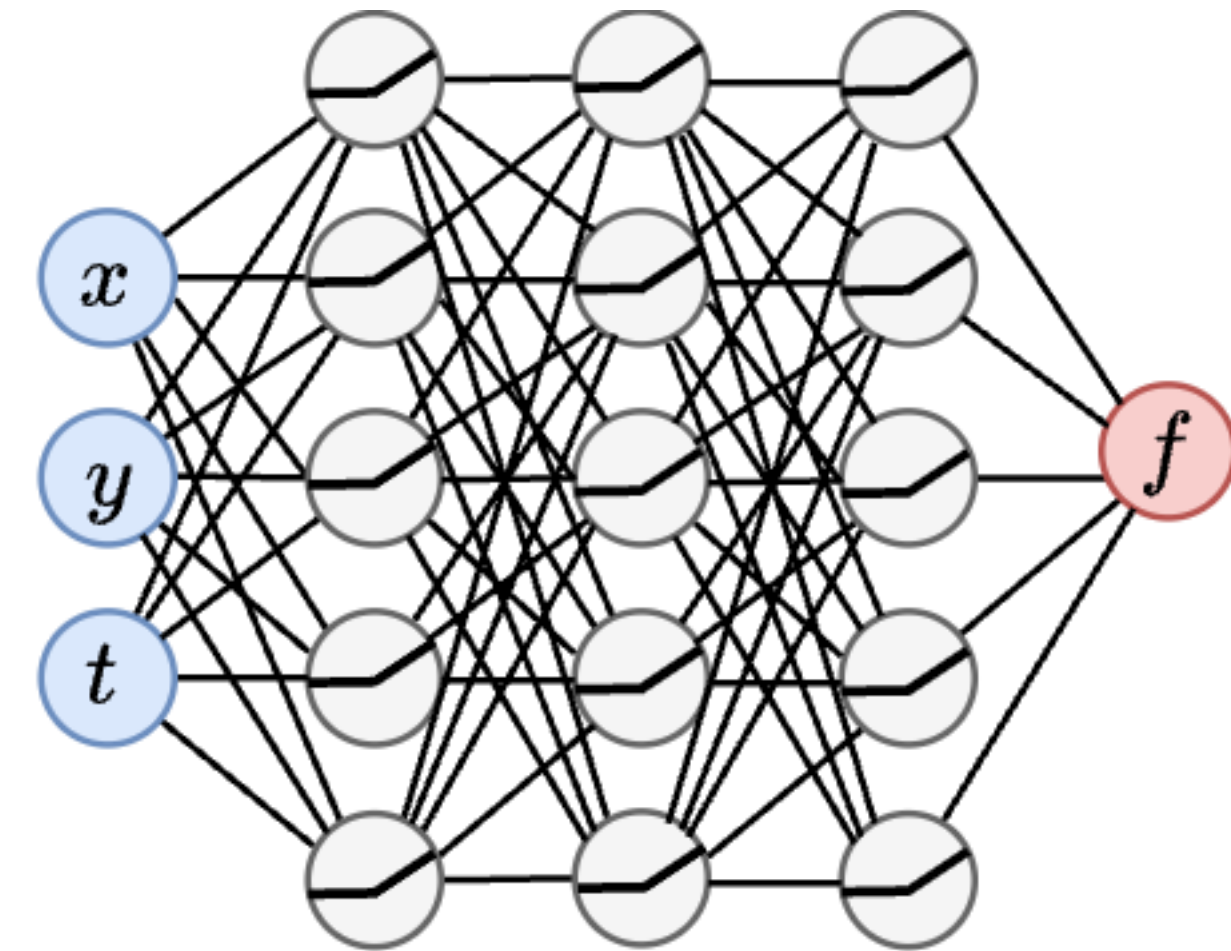
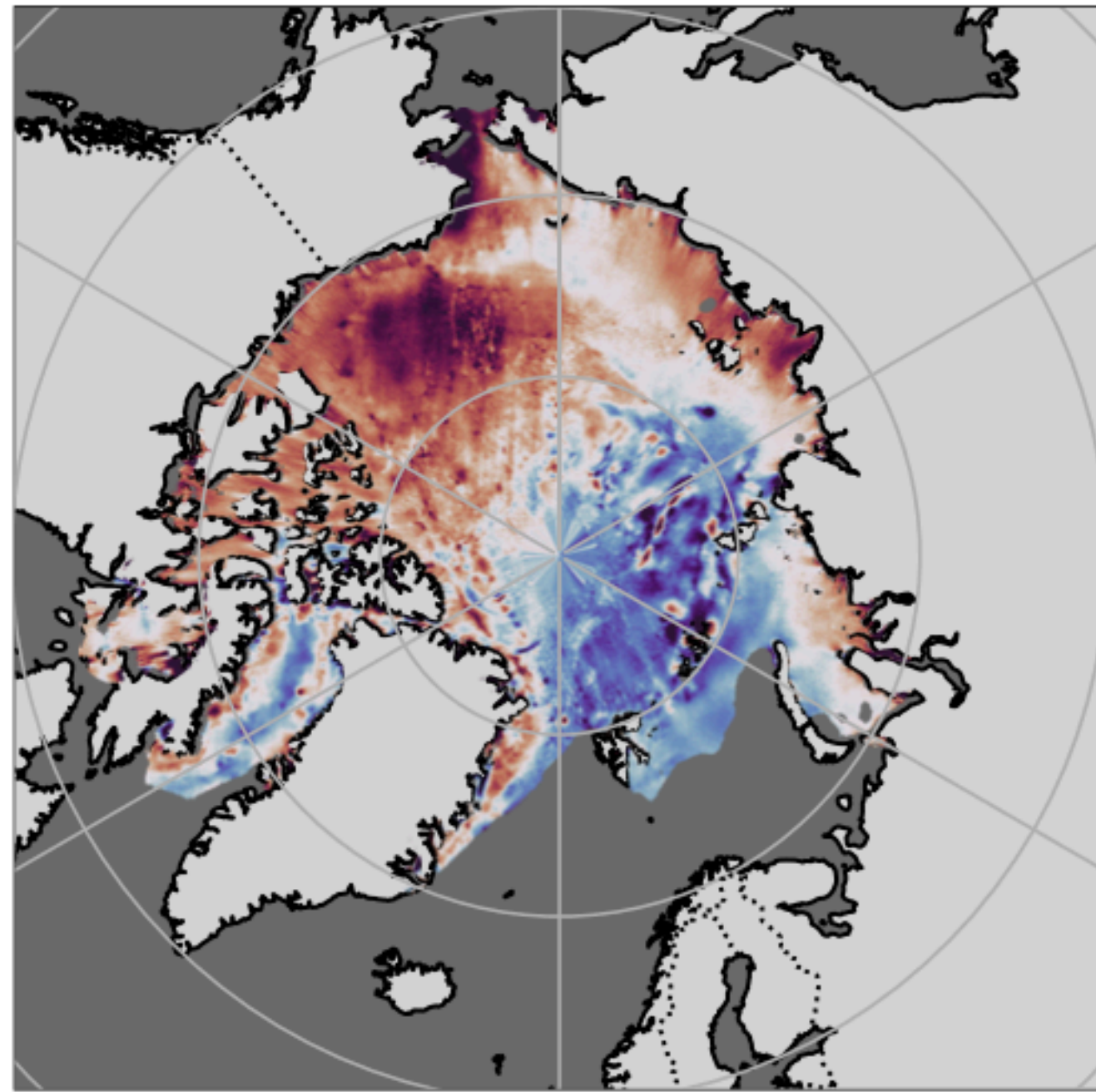
- Cost increases cubically with data
- Stationarity often assumed
- It's Gaussian

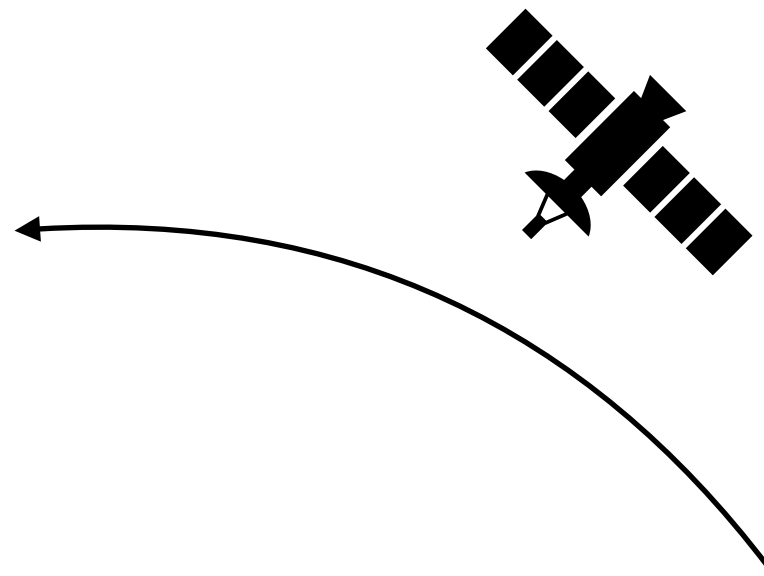
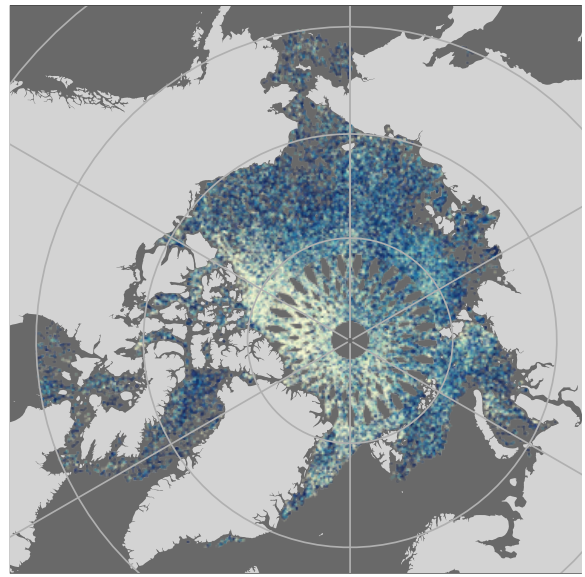
**Can we use neural networks  
instead?**



Inputs:  $(x, y, t)$   
Outputs:  $f(x, y, t) + \epsilon$

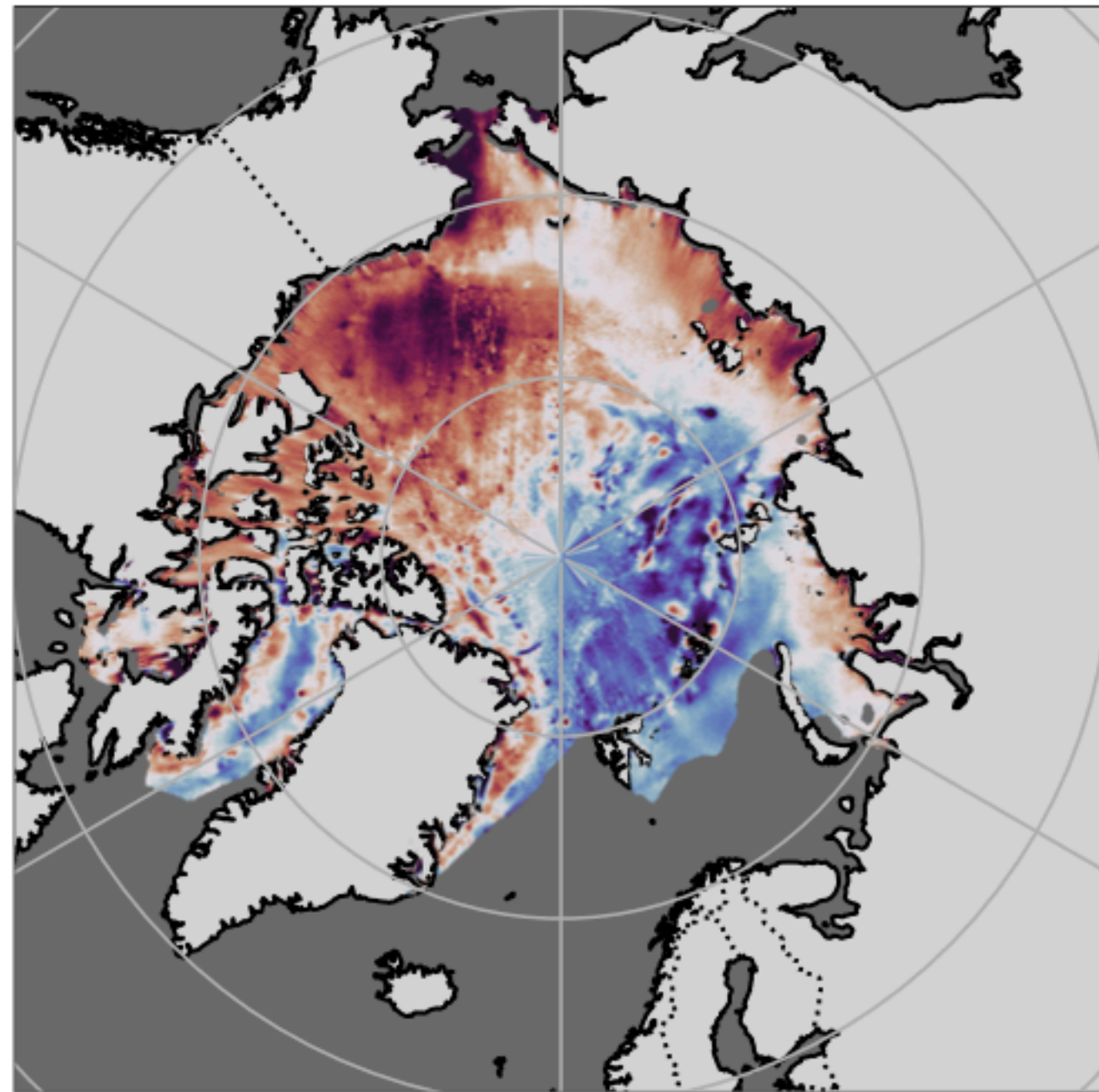
Ground Truth



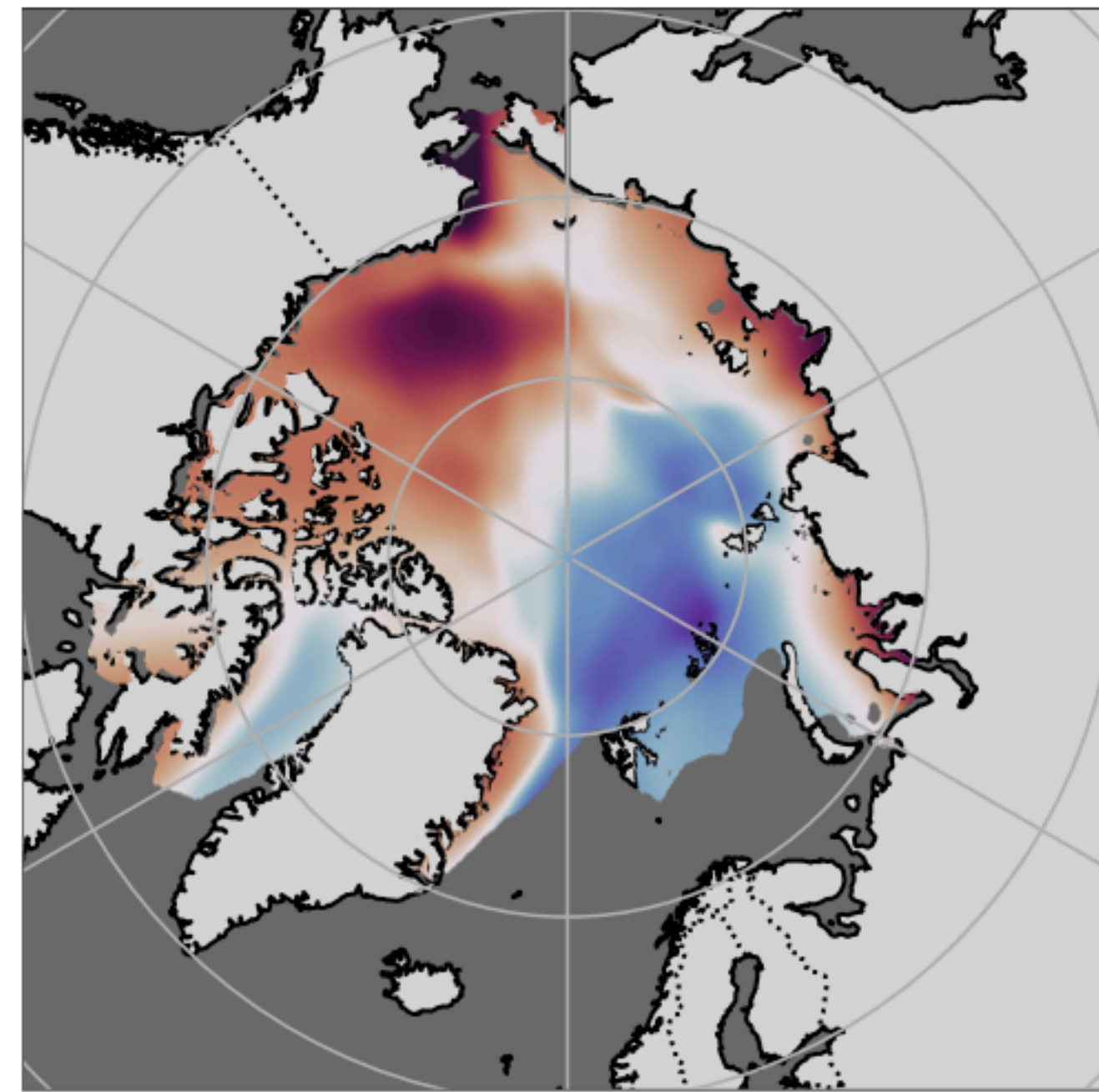


Inputs:  $(x, y, t)$   
Outputs:  $f(x, y, t) + \epsilon$

Ground Truth



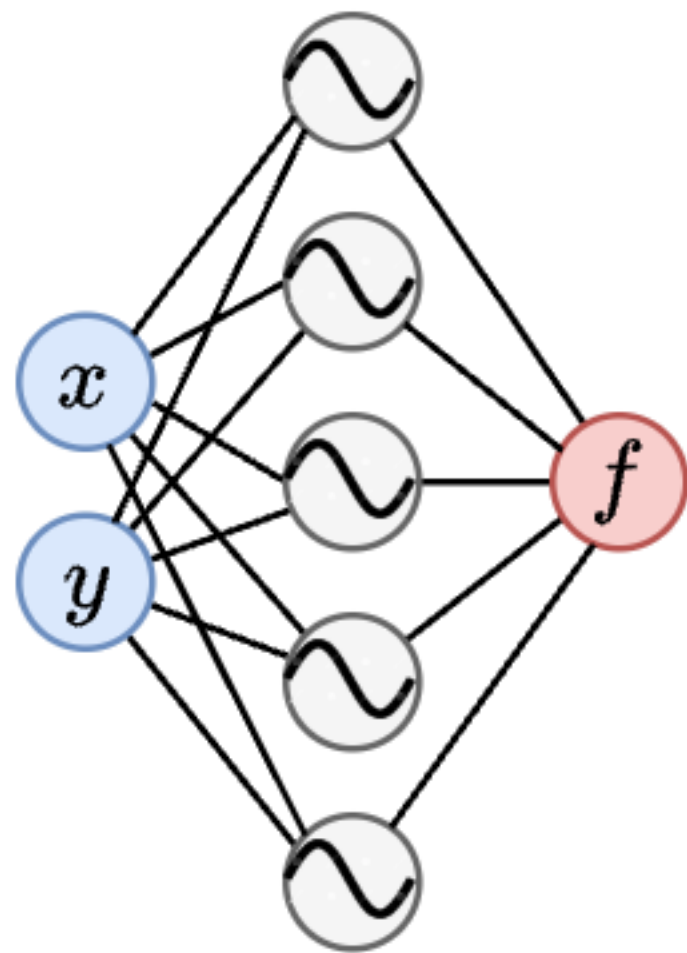
Mean: ReLU MLP



# Random features revisited

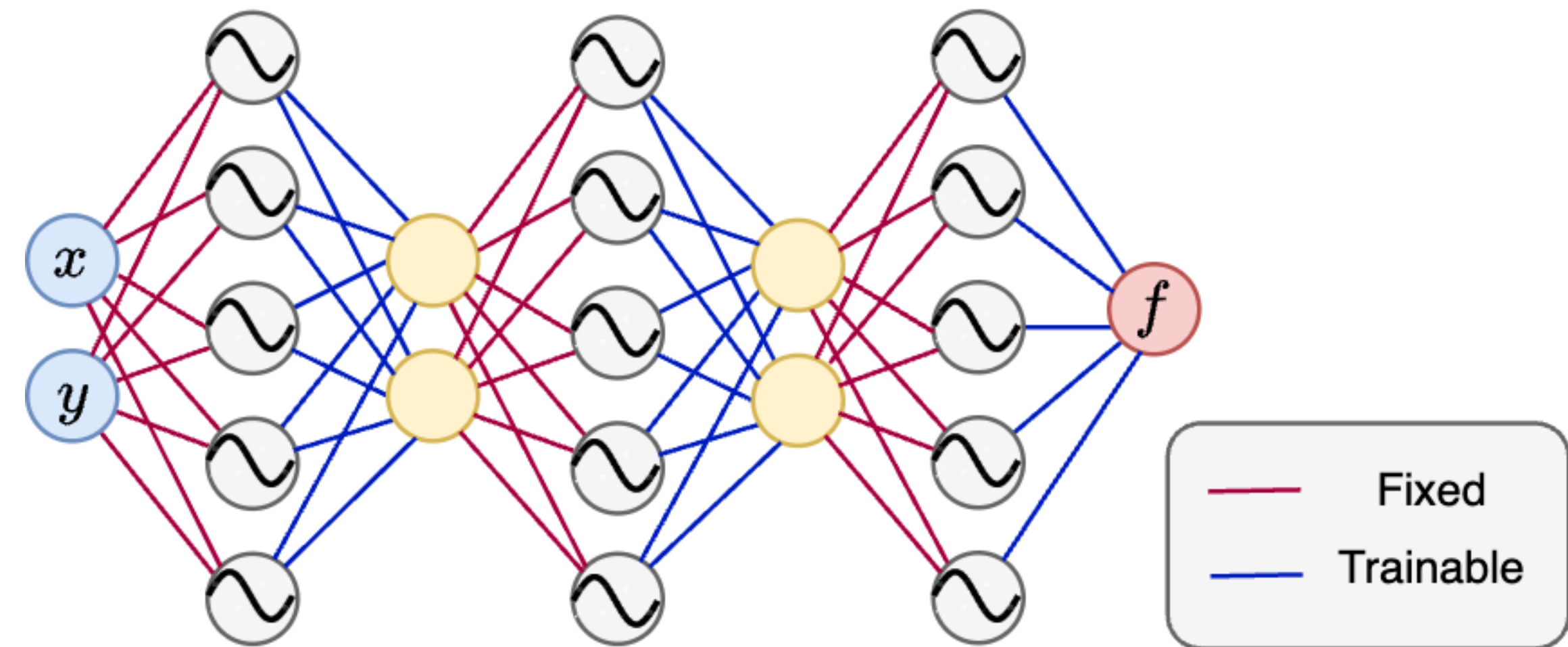
Recall that a Matérn GP  $f$  has the **random feature representation**:

$$f(x) \approx \sum_{m=1}^M \theta_m \psi_m(x), \quad \text{where } \psi_m(x) = \sqrt{\frac{2\sigma^2}{M}} \cos(\omega_m^\top x + b_m).$$
$$\omega_m \sim t_{2\nu}(0, \ell^{-2}), \quad b_m \sim U([0, 2\pi]) \quad \text{and} \quad \theta_m \sim \mathcal{N}(0, 1).$$



**Idea:**

Make it deep!



Similar to the SIREN architecture.



# Spherical Random Features

Recall the Riemannian Matérn kernel on  $\mathbb{S}^2$ :

$$k(x, x') = \frac{\sigma^2}{C_{\nu, \ell}} \sum_{n=0}^{\infty} \left( \frac{2\nu}{\ell^2} + \lambda_n \right)^{-\nu - d/2} \phi_n(x) \phi_n(x'),$$

where  $\lambda_n = n(n + 1)$  and  $\phi_n(x) = \{ Y_n^1(x), \dots, Y_n^{2n+1}(x) \}$ .

This implies *deterministic feature maps*

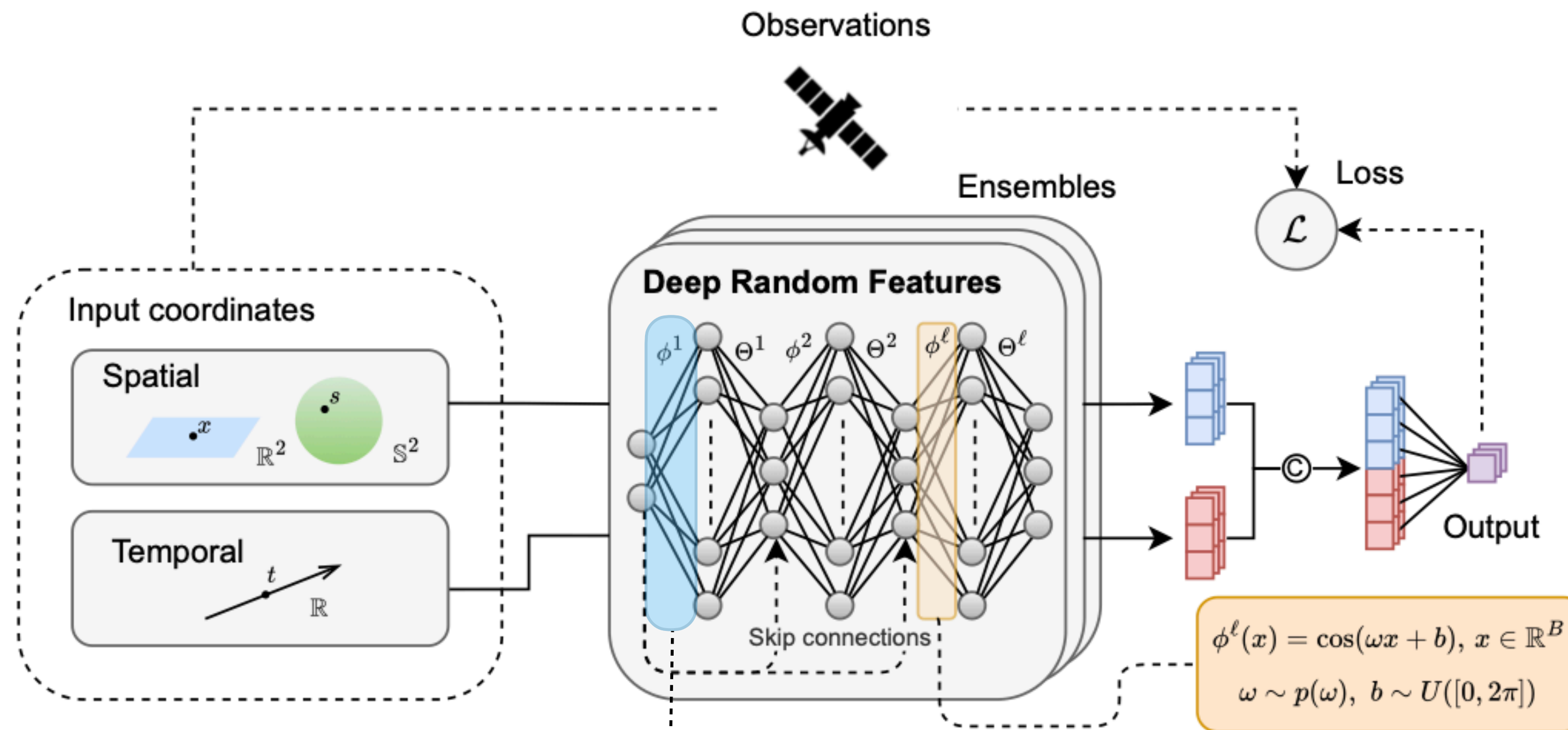
$$\psi_{n,m}(x) = \sqrt{\frac{\sigma^2}{C_{\nu, \ell}}} \left( \frac{2\nu}{\ell^2} + n(n + 1) \right)^{\frac{-\nu - d/2}{2}} Y_n^m(x).$$

$$\begin{aligned}
k(x, x') &\approx \frac{Z_N \sigma^2}{C_{\nu, \ell}} \sum_{n=0}^N \sum_{m=1}^{2n+1} \rho(n) Y_n^m(x) Y_n^m(x'), \quad \text{where} \quad \rho(n) := \frac{1}{Z_N} \left( \frac{2\nu}{\ell^2} + n(n+1) \right)^{-\nu-d/2} \\
&= \frac{Z_N \sigma^2}{C_{\nu, \ell}} \sum_{n=0}^N \rho(n) \left( \sum_{m=1}^{2n+1} Y_n^m(x) Y_n^m(x') \right) \\
&\propto \sum_{n=0}^N \rho(n) \mathcal{G}_n^{1/2}(\cos(\langle x, x' \rangle)) \\
&= \sum_{n=0}^N \rho(n) \int_{\mathbb{S}^2} \mathcal{G}_n^{1/2}(\cos(\langle x, b \rangle)) \mathcal{G}_n^{1/2}(\cos(\langle x', b \rangle)) db \\
&= \mathbb{E}_{\omega, b} \left[ \mathcal{G}_{\omega}^{1/2}(\cos(\langle x, b \rangle)) \mathcal{G}_{\omega}^{1/2}(\cos(\langle x', b \rangle)) \right], \quad \omega \sim \text{Multinomial}(\rho(1), \dots, \rho(N)), \quad b \sim U(\mathbb{S}^2) \\
&\approx \frac{1}{J} \sum_{j=1}^J \mathcal{G}_{\omega_j}^{1/2}(\cos(\langle x, b_j \rangle)) \mathcal{G}_{\omega_j}^{1/2}(\cos(\langle x', b_j \rangle)), \quad \omega_j \sim \text{Multinomial}(\rho(1), \dots, \rho(N)), \quad b_j \sim U(\mathbb{S}^2)
\end{aligned}$$

This implies **spherical random features**

$$\psi_j(x) \propto \mathcal{G}_{\omega_j}^{1/2}(\cos(\langle x, b_j \rangle)).$$

# Deep random features



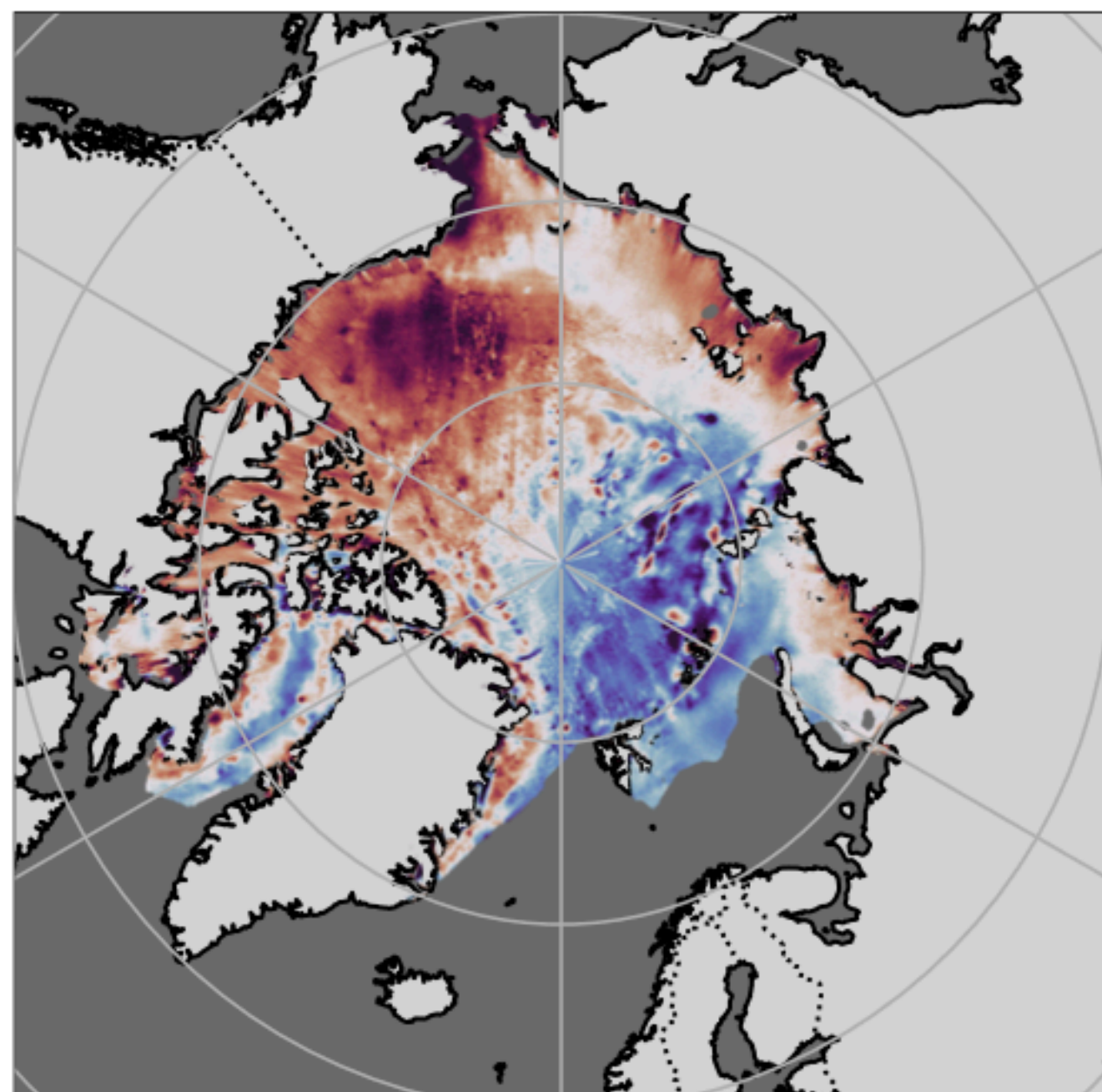
## Notes:

- Use deep ensembles to estimate uncertainty
- Use batched stochastic gradient optimisation
- Tune kernel hyperparameters on validation set

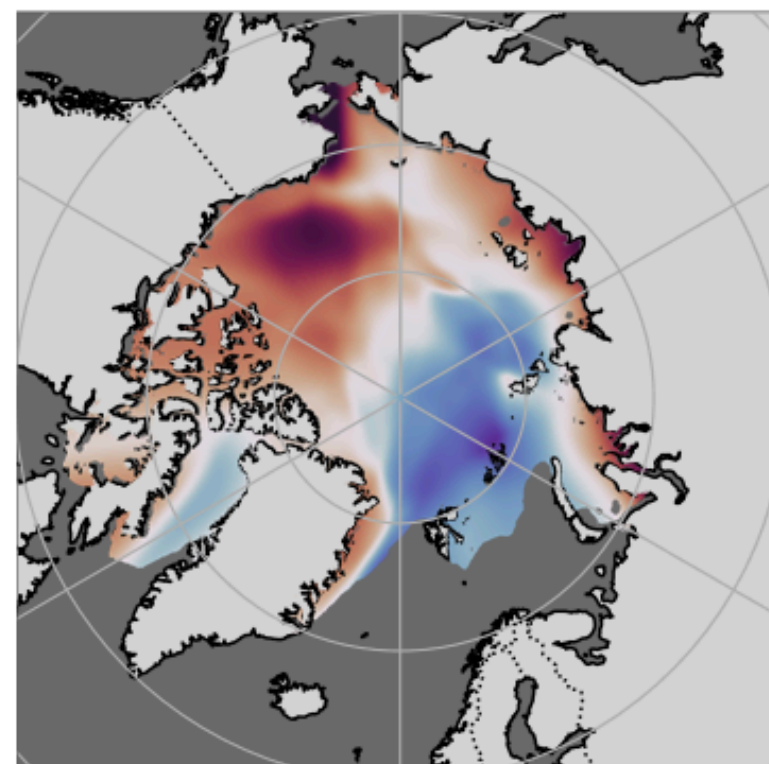
If  $x \in \mathbb{R}^d$ ,  $\phi^1(x) = \cos(\omega x + b)$ , where  $\omega \sim t_{2\nu}(0, \ell^{-2})$ ,  $b \sim U([0, 2\pi])$

If  $x \in S^2$ ,  $\phi^1(x) = \mathcal{G}_\omega^{1/2}(\cos(\langle x, b \rangle))$ , where  $\omega \sim \text{Multinomial}(\rho(1), \dots, \rho(N))$ ,  $b \sim U(S^2)$

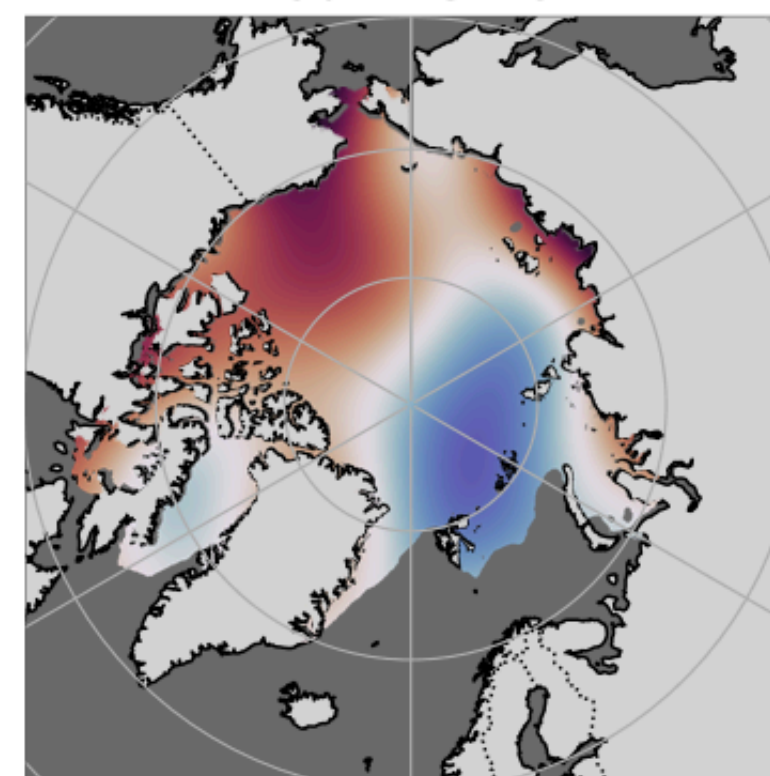
Ground Truth



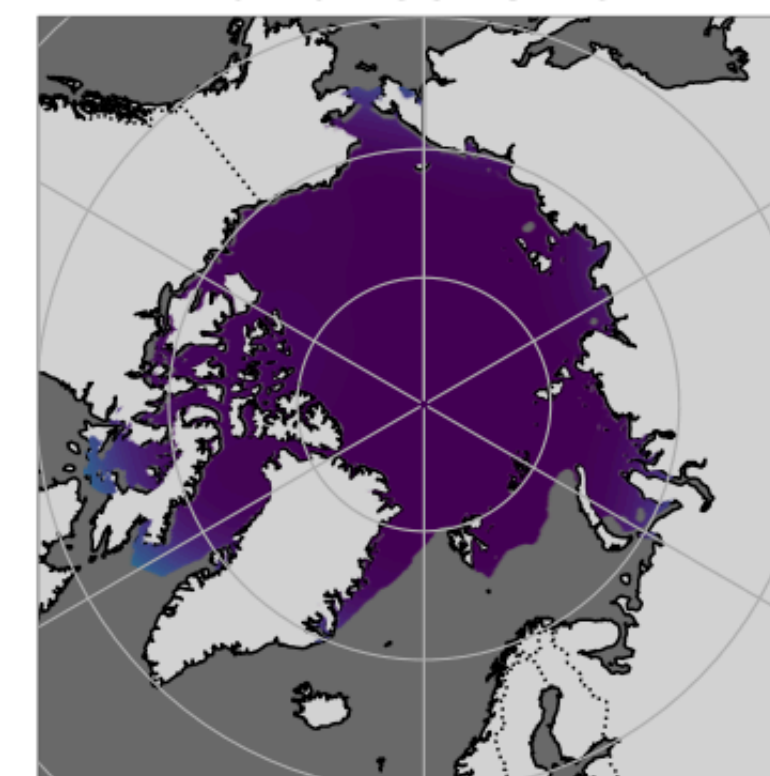
Mean: ReLU MLP



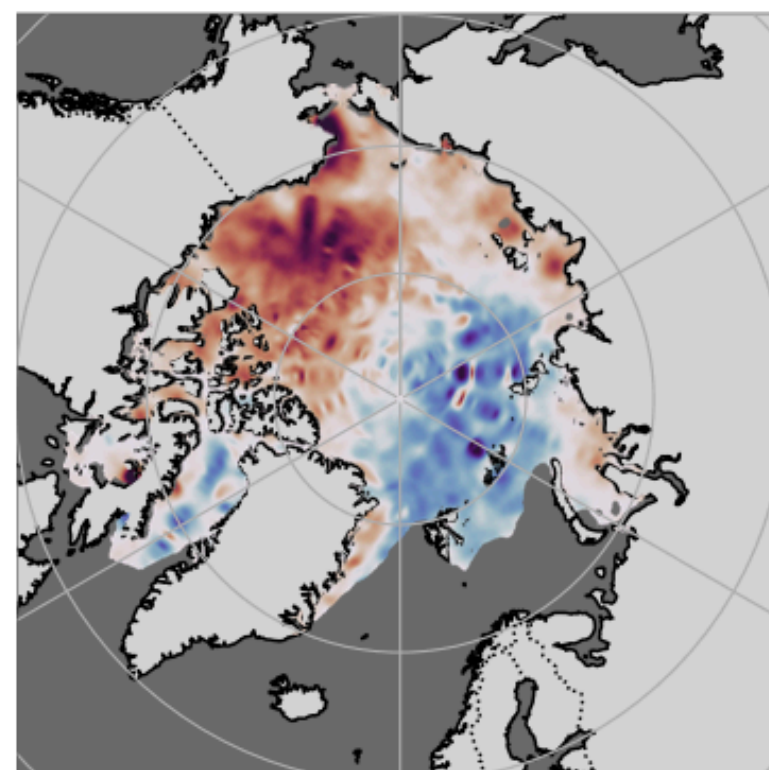
Mean: SVGP



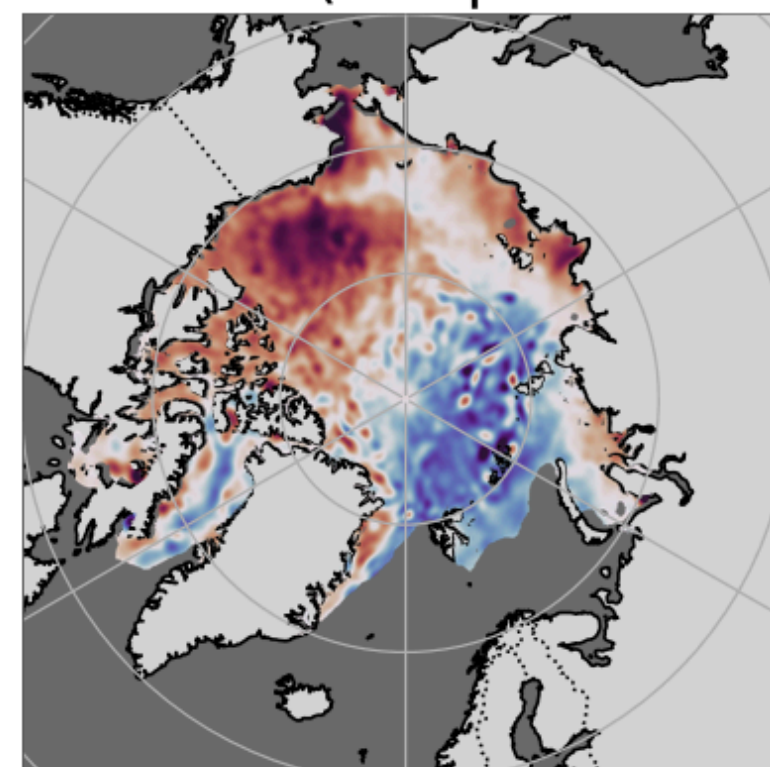
Variance: SVGP



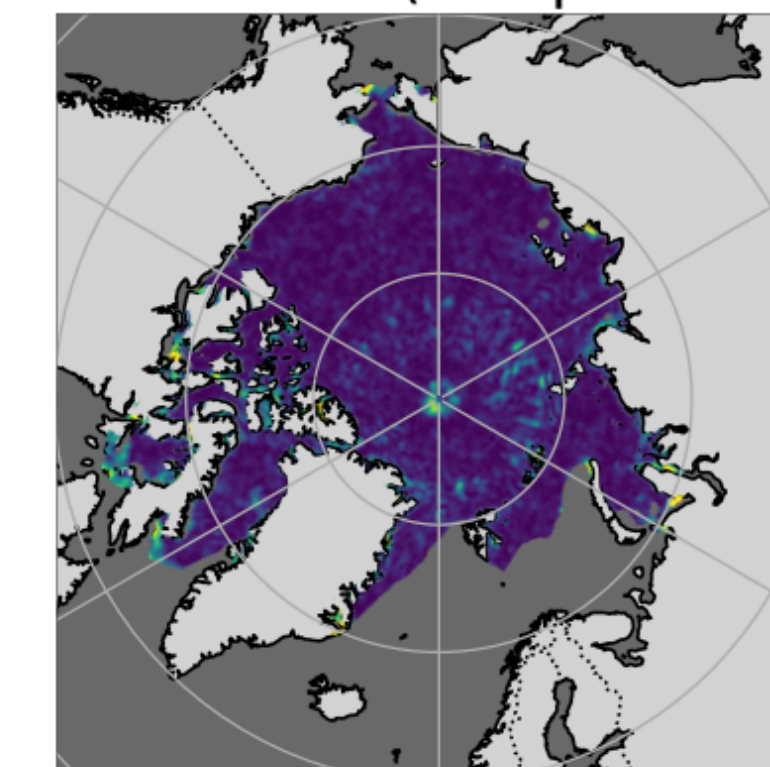
Mean: SIREN



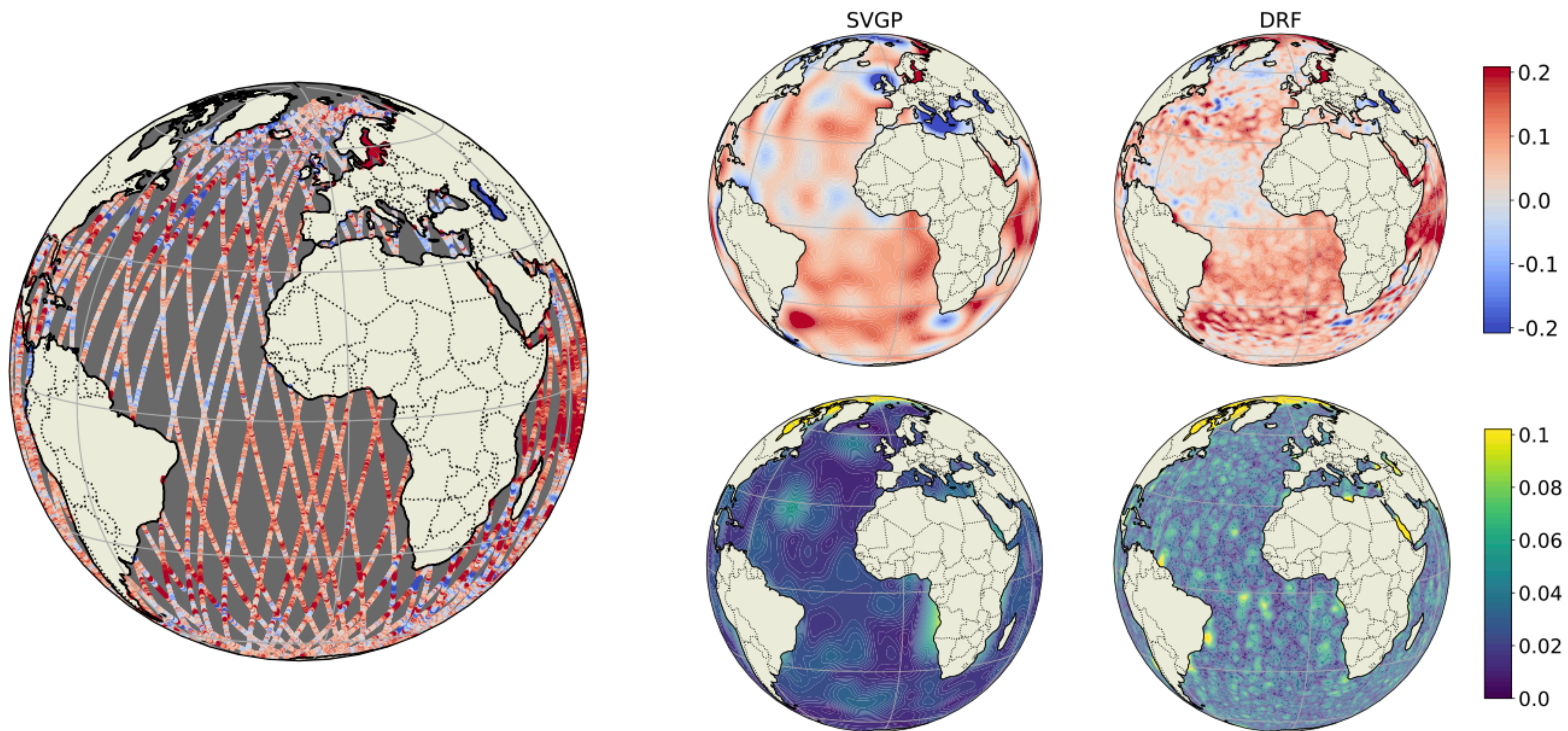
Mean: DRF (Deep ensemble)



Variance: DRF (Deep ensemble)

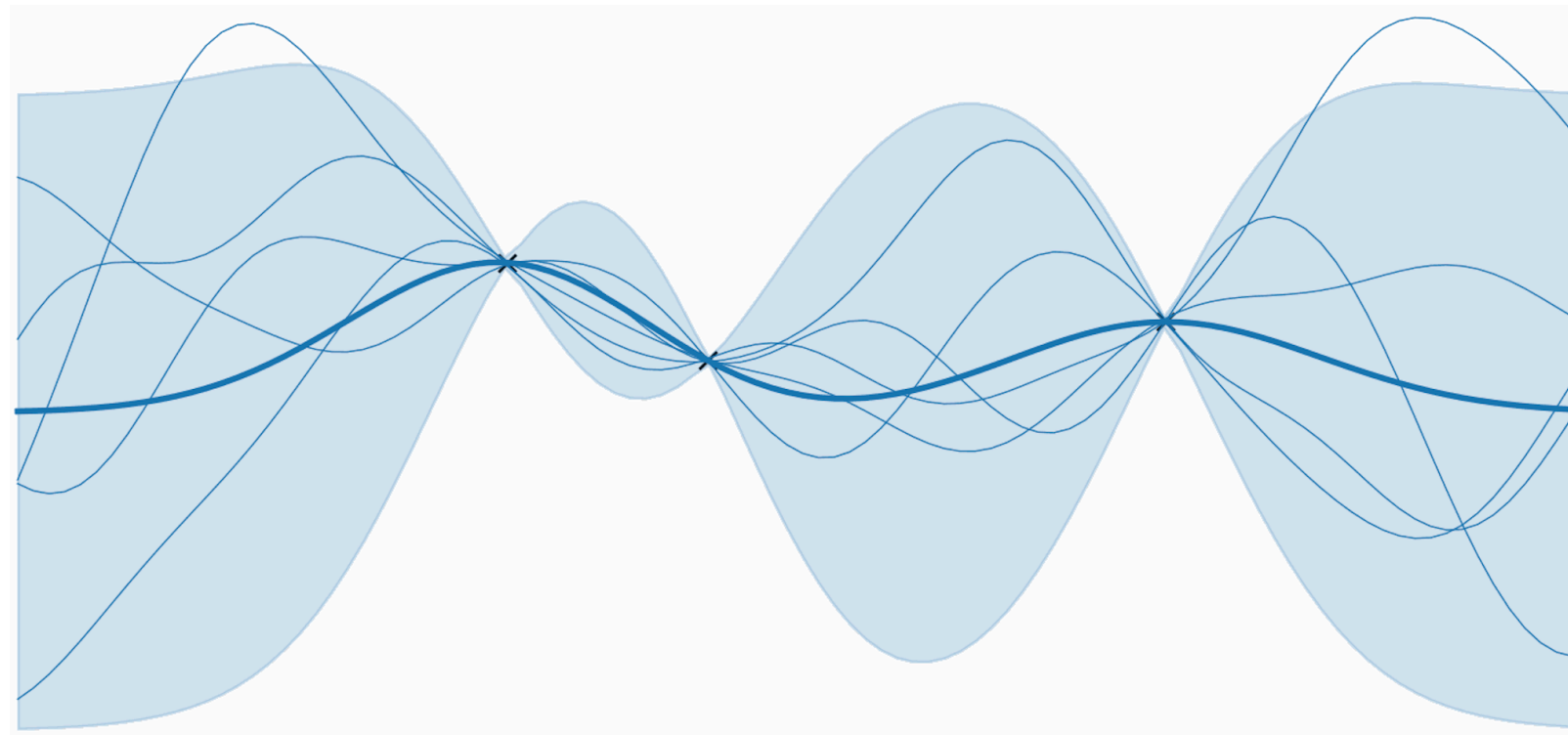


# Global sea level interpolation



# Summary

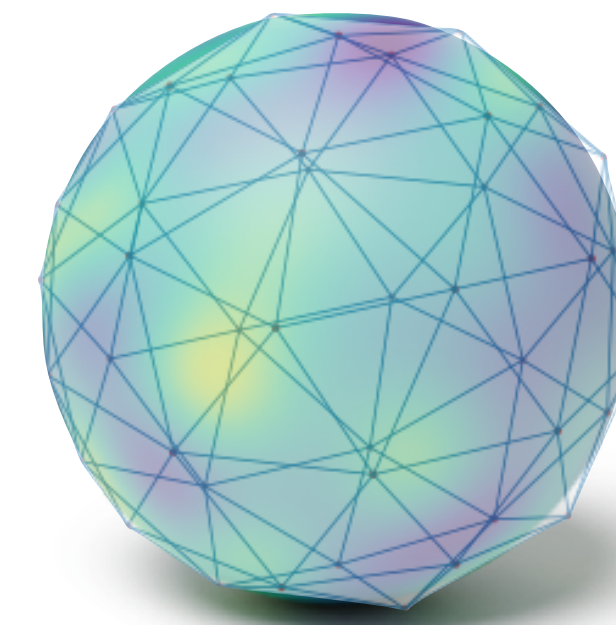
# Summary



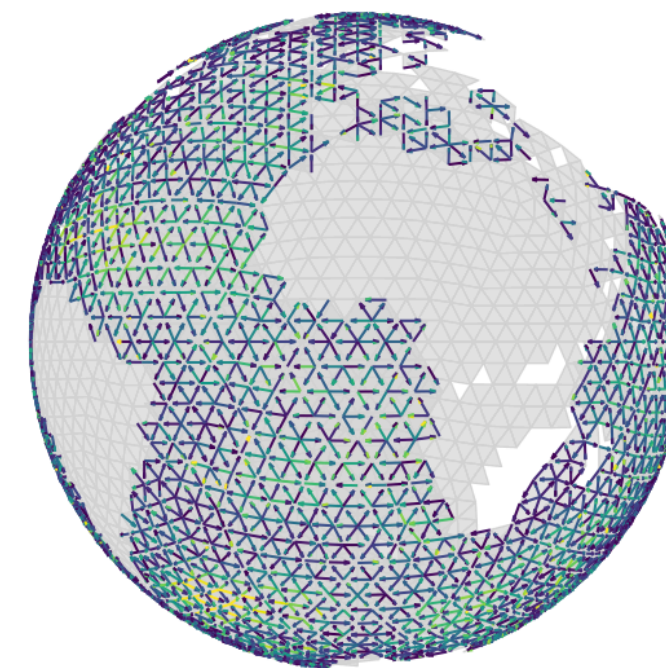
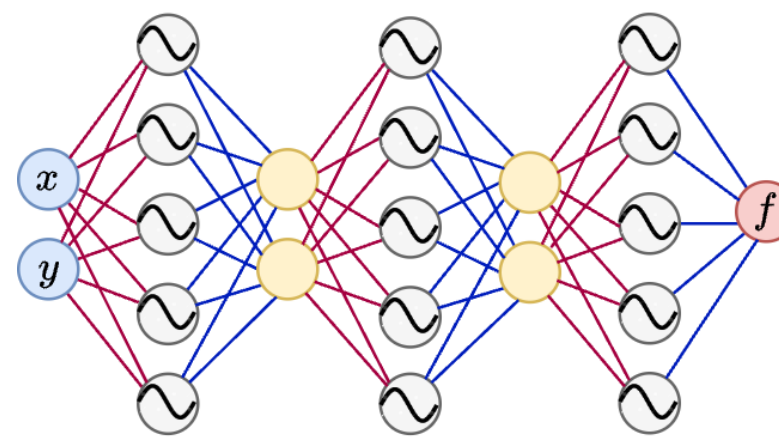
Introduced Matérn Gaussian processes

1. SPDE formulation
2. Weight-space perspective / random features

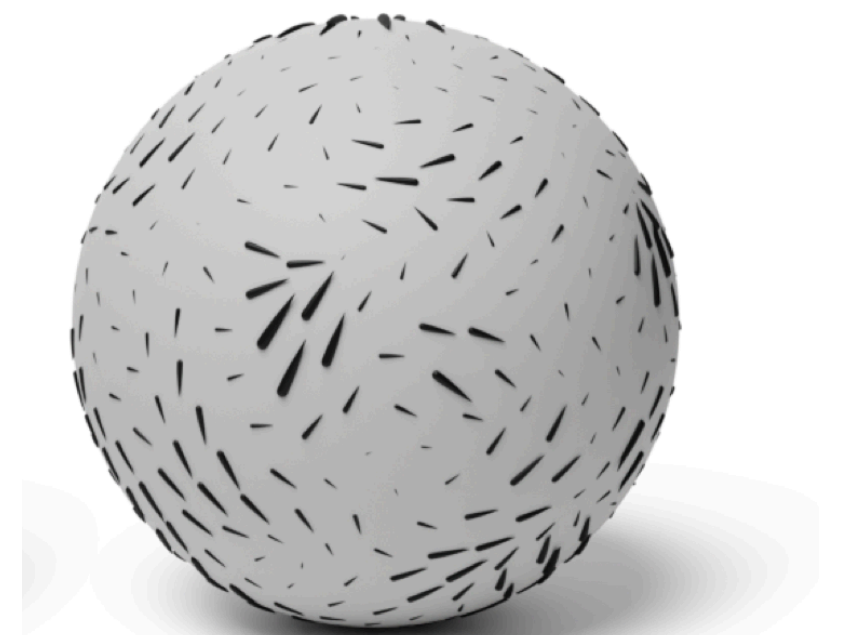
$$\left(\frac{2\nu}{\ell^2} - \Delta\right)^{\frac{\nu+d/2}{2}} f = \mathcal{W}_\sigma$$



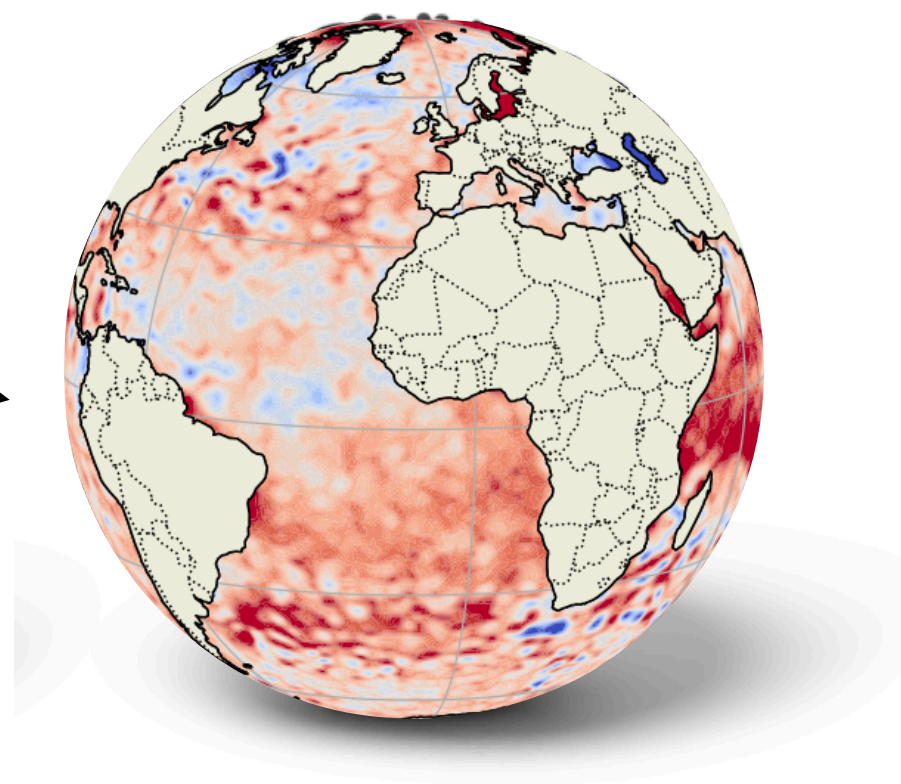
Extend to Riemannian manifolds / graphs via the SPDE framework



Embedding-free approach to modelling vector fields using Matérn cochains



Extended to vector fields by combining multiple Riemannian Matérn GPs in embedding space

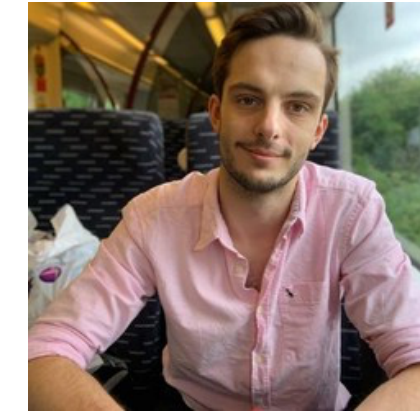


Stacked random feature representations of Matérn GPs

# Thank you collaborators

Hutchinson et al. "Vector-valued Gaussian Processes on Riemannian Manifolds via Gauge Equivariant Projected Kernels." *NeurIPS 2021*

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Michael Hutchinson



Alex Terenin



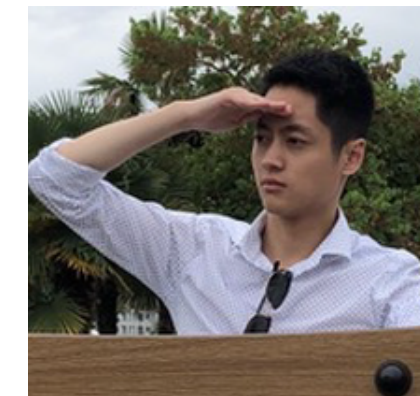
Slava Borovitskiy



Yee Whye Teh

Alain et al. "Gaussian Processes on Cellular Complexes." *ICML 2024*

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Mathieu Alain



Brooks Paige

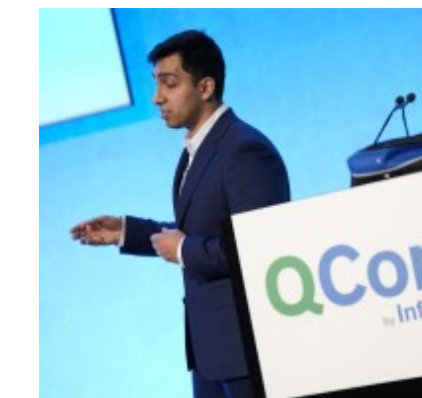


Marc Deisenroth

Chen et al. "Deep Random Features for Scalable Interpolation of Spatiotemporal Data." *Submitted to ICLR 2025*



Weibin Chen



Azhir Mahmood



Michel Tsamados

